



AP-275

**APPLICATION
NOTE**

**An FFT Algorithm For
MCS®-96 Products Including
Supporting Routines and
Examples**

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**AN FFT ALGORITHM FOR
MCS®-96 PRODUCTS
INCLUDING SUPPORTING
ROUTINES AND
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1.0 INTRODUCTION

Intel's 8096 is a 16-bit microcontroller with processing power sufficient to perform many tasks which were previously done by microprocessors or special building block computers. A new field of applications is opened by having this much power available on a single chip controller.

The 8096 can be used to increase the performance of existing designs based on 8051s or similar 8-bit controllers. In addition, it can be used for Digital Signal Processing (DSP) applications, as well as matrix manipulations and other processing oriented tasks. One of the tasks that can be performed is the calculation of a Fast Fourier Transform (FFT). The algorithm used is similar to that in many DSP and matrix manipulation applications, so while it is directly applicable to a specific set of applications, it is indirectly applicable to many more.

FFTs are most often used in determining what frequencies are present in an analog signal. By providing a tool to identify specific waveforms by their frequency components, FFTs can be used to compare signals to one another or to set patterns. This type of procedure is used in speech detection and engine knock sensors. FFTs also have uses in vision systems where they identify objects by comparing their outlines, and in radar units to detect the dopler shift created by moving objects.

This application note discusses how FFTs can be calculated using Intel's MCS®-96 microcontrollers. A review of fourier analysis is presented, along with the specific code required for a 64 point real FFT. Throughout this application note, it is assumed that the reader has a working knowledge of the 8096. For those without this background the following two publications will be helpful:

1986 Microcontroller Handbook
Using the 8096, AP-248

These books are listed in the bibliography, along with other good sources of information on the MCS-96 product family and on Fast Fourier Transforms.

2.0 PROGRAM OVERVIEW

This application note contains program modules which are combined to create a program which performs an FFT on an analog signal sampled by the on-board ADC (Analog to Digital Converter) of the 8097. The results of the FFT are then provided over the serial

channel to a printer or terminal which displays the results. In the applications listed in the previous section, the data from this FFT program would be used directly by another program instead of being plotted. However, the plotted results are used here to provide an example of what the FFT does. There are four program modules discussed in this application note:

FFTRUN - Runs a 64 point FFT on its data buffer. It produces 32 14-bit complex output values and 32 14-bit output magnitudes. A fast square root routine and log conversion routine are included.

A2DCON - Fills one of two buffers with analog values at a set sample rate. The sample time can be as fast as 50 microseconds using 8x9xBH components.

PLOTSP - Plots the contents of a buffer to a serially connected printer. Routines are provided for console out and hexadecimal to decimal conversion and printing.

FTMAIN - The main module which controls the other modules.

Each of the modules will be described separately. In order to better understand how the programs work together, a brief tutorial on FFTs will be presented first, followed by descriptions of the programs in the order listed above.

The final program uses 64 real data points, taken from either a table or analog input 1. Each of the data points is a 16-bit signed number. The processing takes 12.5 milliseconds when internal RAM is used as the data space. If external RAM is used, 14 milliseconds are required. Larger FFTs can be performed by slightly modifying the programs. A 256-point FFT would take approximately 65 milliseconds, and a 1024-point version would require about 300 milliseconds.

In the program presented, the analog sampling time is set for 1 sample every 100 microseconds, providing the 64 samples in 6.4 milliseconds. The sampling time can be reduced to around 60 microseconds per point by changing a variable, and less than 50 microseconds by using the 8x9xBH series of parts, since they have a 22 microsecond A to D conversion time.

The programs are set up to be run in a sequence instead of concurrently. This provides the fastest operation if the sampling speed were reduced to the minimum possible. For the fastest operation above about 80 microseconds a sample, the programs could be run concurrently, but this would require some minor modifications of the program. Figure 1 shows the timing of the program as presented.

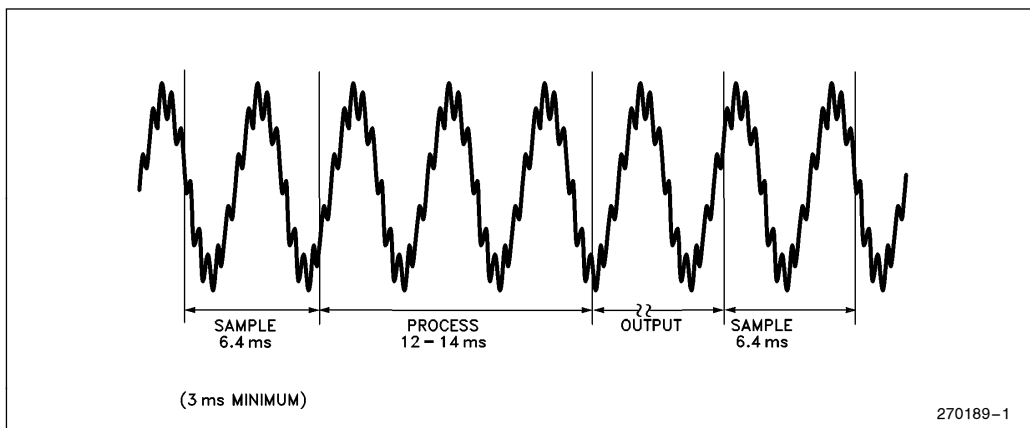


Figure 1. Timing of the FFT Program

These programs have run in the Intel Microcontroller Operation Application's Lab and produced the results presented in this application note. Since the programs have not undergone any further testing, we cannot guarantee them to be bug proof. We, therefore, recommend that they be thoroughly tested before being used for other than demonstration purposes.

3.0 FOURIER TRANSFORMS

A Fourier Transform is a useful analytical tool that is frequently ignored due to its mathematically oriented derivations. This is unfortunate, since Fourier transforms can be used without fully understanding the mathematics behind them. Of course, if one understands the theory behind these transforms, they become much more powerful.

The majority of this application note deals with how a Fast Fourier Transform (FFT) can be used for spectrum analysis. This procedure takes an input signal and separates it into its frequency components. One can almost treat the FFT as a black box, which has as its output, the frequency components and magnitudes of the input signal, much like a spectrum analyzer.

From a mathematical standpoint, Fourier Transforms change information in the time domain into the frequency domain. The theory behind the Fourier transform stems from Fourier analysis, also called frequency analysis.

There are many books on the topic of Fourier analysis, several of which are listed in the bibliography. In this application note, only the pertinent formulas and uses will be presented, not their derivations.

The main idea in Fourier analysis is that a function can be expressed as a summation of sinusoidal functions of different frequencies, phase angles, and magnitudes. This idea is represented by the Fourier Integral:

$$H(f) = \int_{-\infty}^{\infty} h(t) e^{-j2\pi ft} dt \quad (1)$$

Where: $H(f)$ is a function of frequency
 $h(t)$ is a function of time

Since

$$e^{-j\theta} = \cos \theta - j \sin \theta \quad (2)$$

$$H(f) = \int_{-\infty}^{\infty} h(t) (\cos (2\pi ft) - j \sin (2\pi ft)) dt \quad (3)$$

Figure 2 shows a rectangular pulse and its Fourier transform. Note that the results in the frequency domain are continuous rather than discrete. The horizontal axis in Figure 2a is frequency, while that of Figure 2b is time.

In a simplified case, the varying phase angles can be removed, and the integral changed to a summation, known as a Fourier Series. All periodic functions can be described in this way. This series, as shown below, can help provide a more graphical understanding of Fourier analysis.

$$y(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} [a_n \cos (2\pi n f_0 t) + b_n \sin (2\pi n f_0 t)] \quad (4)$$

for $n = 1$ to ∞

Where $f_0 = \frac{1}{T_0}$, the fundamental frequency.

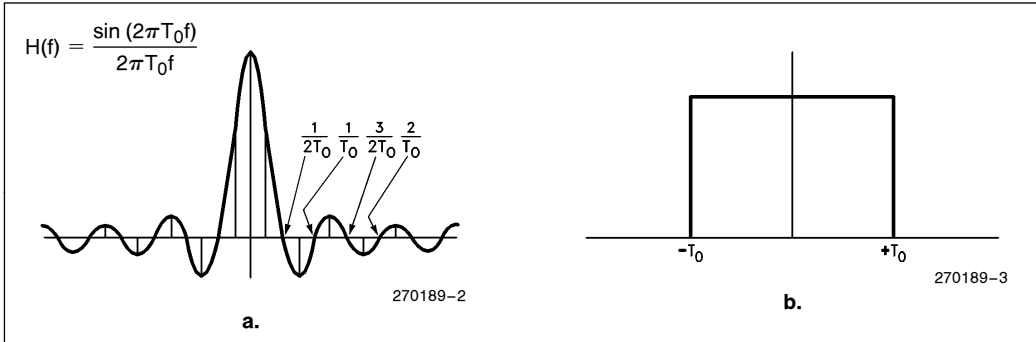


Figure 2. Rectangular Pulse and Its Fourier Transform

This formula can also be represented in complex form as:

$$\sum_{n=-\infty}^{\infty} \alpha_n e^{j2\pi n f_0 t} \quad (5)$$

The Fourier series for a square wave is

$$\sum_{k=0}^{\infty} \frac{\sin((2k+1)2\pi f_0 t)}{(2k+1)} \quad (6)$$

If these sinusoids are summed, a square wave will be formed. Figure 3 shows the graphical summation of the first 3 terms of the series. Since the higher frequencies contribute to the squareness of the waveform at the corners, it is reasonable to compare only the flatness of the top of the waveform. The sharpness or risetime of the waveform can be determined by the highest fre-

quency term being summed. With rise and fall times of 10% of the period, the waveform generated by the first 3 terms is within 20% of ideal. At 7 terms it is within 10%, and at 20 terms it is within 5%. With a 5% risetime, it is within 20% of ideal after 5 terms, 10% after 13 terms and 5% after 32 terms. Figure 4 shows the resultant waveforms after the summation of 7, 15 and 30 terms.

Fourier analysis can be used on equation 4 to find the coefficients a_n and b_n . To make this process easier to use with a computer, a discrete form, rather than a continuous one, must be used. The discrete Fourier transform, shown in Equation 7, is a good approximation to the continuous version. The closeness of the approximation depends on several conditions which will be discussed later. The input to this transform is a set of N equally spaced samples of a waveform taken over a period of NT . The period NT is frequently referred to as the "Sampling Window".

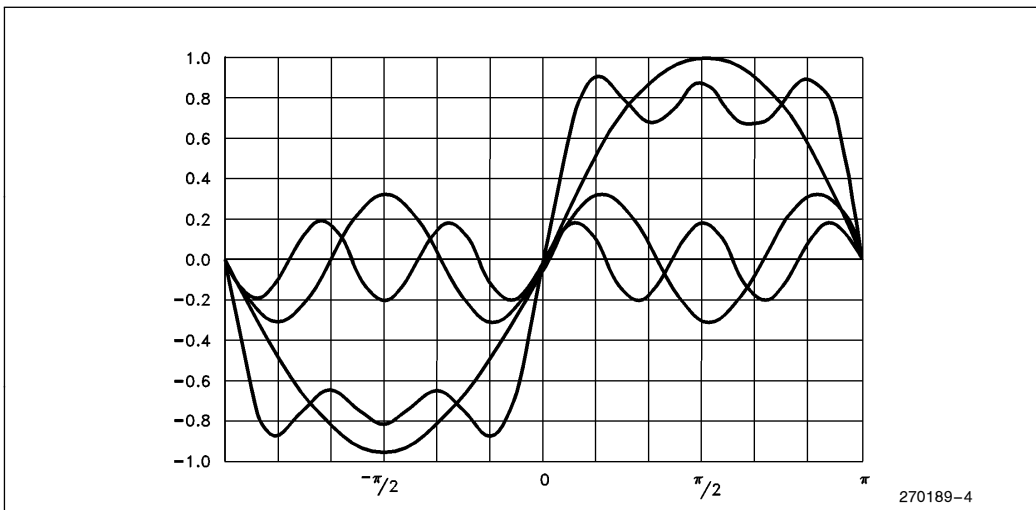
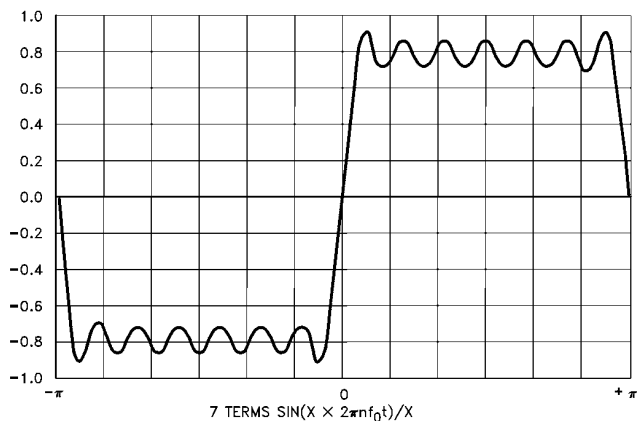
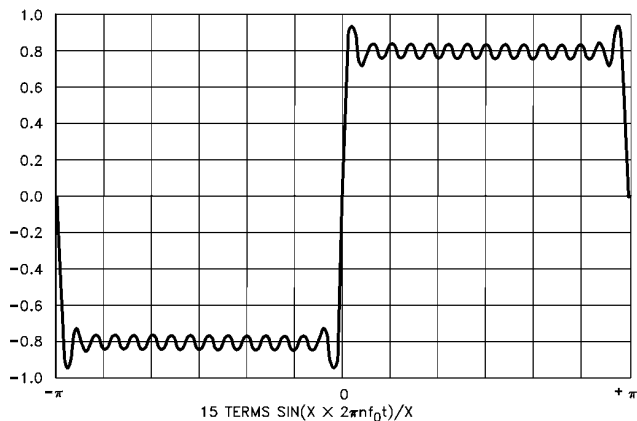


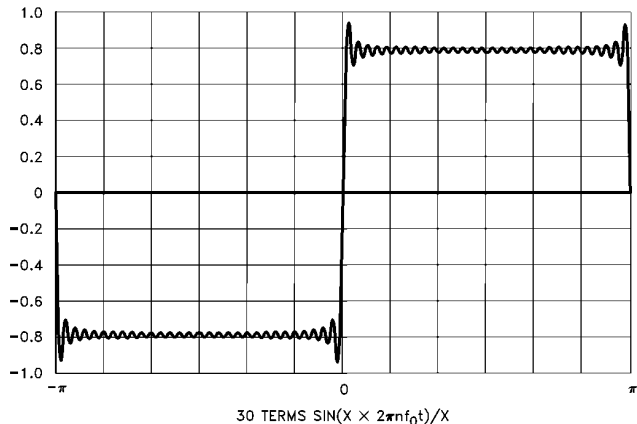
Figure 3. Graphical Summation of Sinewaves



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Figure 4. Square Wave from Sinusoids

$$H\left(\frac{n}{NT}\right) = \sum_{k=0}^{N-1} h(kT)e^{-j2\pi nk/N}$$

$n = 0, 1, \dots, N-1$ (7)

Where: $H(f)$ is a function of frequency

$h(t)$ is a function of time

T is the time span between samples

N is the number of samples in the window

$n = 0, 1, 2 \dots N-1$

This transform is used for many applications, including Fourier Harmonic Analysis. This procedure uses the transform to calculate the coefficients used in Equation 5. In order to do this, the factor T/NT must be added to the transform as follows:

$$H\left(\frac{n}{NT}\right) = \frac{T}{(NT)} \sum_{k=0}^{N-1} h(kT) e^{-j2\pi nk/N}$$

$n = 0, 1, 2, 3, \dots, N-1$ (8)

The factor provides compensation for the number of samples taken. Note that the functions $H(f)$ and $h(t)$ are complex variables, so the simplicity of the equation can be misleading. Once the values of $h(t)$ are known, (ie.

the value of the input at the discrete times (t)), the Fourier Transform can be used to find the magnitude and phase shift of the signal at the frequencies (f).

A spectrum analyzer can provide similar information on an analog input signal by using analog filters to separate the frequency components. Regardless of its source, the information on component frequencies of a signal can be used to detect specific frequencies present in a signal or to compare one signal to another. Many lab experiments and product development tests can make use of this type of information. Using these methods, the purity of signals can be measured, specific harmonics can be detected in mechanical equipment, and noise bursts can be classified. All of this information can be obtained while still treating the FFT process as a black box.

Consider the discrete transform of a square wave as shown in Figure 5. Note that the component magnitudes, as shown in the series of Equation 6, are shown in a mirrored form in the transform. This will happen whenever only real data is used as the FFT input, if both real and imaginary data were used the output would not be guaranteed to be symmetrical. For this reason, there is duplicate information in the transform for many applications. Later in this section a method to make the most of this characteristic is discussed.

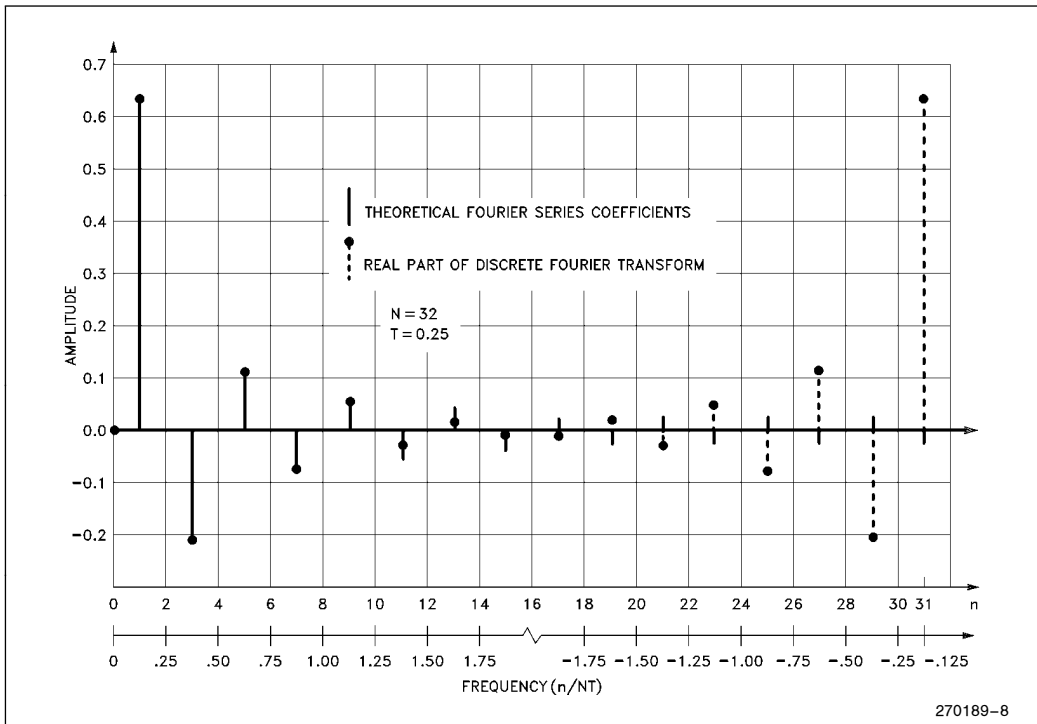


Figure 5. Discrete Transform of a Square Wave

If one looks at Equation 8, it can be seen that the calculation of a discrete Fourier transform requires N squared complex multiplications. If N is large, the calculation time can easily become unrealistic for real-time applications. For example, if a complex multiplication takes 40 microseconds, at $N = 16$, 10 milliseconds would be used for calculation, while at $N = 128$, over half a second would be needed. A Fast Fourier Transform is an algorithm which uses less multiplications, and is therefore faster. To calculate the actual time savings, it is first necessary to understand how a FFT works.

4.0 THE FFT ALGORITHM

The FFT algorithm makes use of the periodic nature of waveforms and some matrix algebra tricks to reduce the number of calculations needed for a transform. A more complete discussion of this is in Appendix A, however, the areas that need to be understood to follow the algorithm are presented here. This information need not be read if the reader's intent is to use the program and not to understand the mathematical process of the algorithm

To simplify notation the following substitutions are made in Equation 8.

$$W = e^{-j2\pi/N}$$

$$k = kT$$

$$n = \frac{n}{NT}$$

The resultant equation being

$$x(n) = \sum_{k=0}^{N-1} n(k)W^{nk} \quad (9)$$

Expressed as a matrix operation

$$\begin{bmatrix} X(1) \\ X(2) \\ X(3) \\ \vdots \\ X(N-1) \end{bmatrix} = \begin{bmatrix} W^0 & W^0 & W^0 & \dots & W^0 \\ W^0 & W^1 & W^2 & \dots & W^N \\ W^0 & W^2 & W^4 & \dots & W^{2N} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ W^0 & W^{N-1} & W^{2(N-1)} & \dots & W^{(N-1)^2} \end{bmatrix} \begin{bmatrix} X_0(0) \\ X_0(1) \\ X_0(2) \\ \vdots \\ X_0(N-1) \end{bmatrix}$$

A brief review of matrix properties can be found in Appendix A. Because of the periodic nature of W the following is true:

$$\begin{aligned} W^{nk \text{ MOD } N} &= W^{nk} \\ &= \cos(2\pi nk/N) - j \sin(2\pi nk/N) \end{aligned} \quad (10)$$

$$W^0 = 1 \text{ therefore, if } nk \text{ MOD } N = 0, W^{nk} = 1$$

This reduces the calculations as several of the W terms go to 1 and the highest power of W is N . All of W values are complex, so most of the operations will have to be complex operations. We will continue to use only the W , $X(n)$ and $X_0(k)$ symbols to represent these complex quantities.

The FFT algorithm we will use requires that N be an integral power of 2. Other FFT algorithms do not have this restriction, but they are more complex to understand and develop. Additionally, for the relatively small values of N we are using this restriction should not provide much of a problem. We will define EXPO-NENT as log base 2 of N . Therefore,

$$N = 2^{\text{EXPONENT}}$$

The magic of the FFT, (as detailed in Appendix A), involves factoring the matrix into EXPONENT matrices, each of which has all zeros except for a 1 and a W^{nk} term in each row. When these matrices are multiplied together the result is the same as that of the multiplication indicated in Equation 9, except that the rows are interchanged and there are fewer non-trivial multiplications. To reorder the rows, and thus make the information useful, it is necessary to perform a procedure called "Bit Reversal".

This process requires that N first be converted to a binary number. The least significant bit (lsb) is swapped with the most significant bit (msb). Then the next lsb is swapped with the next msb, and so on until all bits have been swapped once. For $N = 8$, 3 bits are used, and the values for N and their bit reversals are shown below:

Number	Binary	Bit Reversal	Decimal BR
0	000	000	0
1	001	100	4
2	010	010	2
3	011	110	6
4	100	001	1
5	101	101	5
6	110	011	3
7	111	111	7

Recall that the FFT of real data provides a mirrored image output, but the FFT algorithm can accept inputs with both real and imaginary components. Since the inputs for harmonic analysis provided by a single A to D are real, the FFT algorithm is doing a lot of calculations with one input term equal to zero. This is obviously not very efficient. More information for a given size transform can be obtained by using a few more tricks.

It is possible to perform the FFT of two real functions at the same time by using the imaginary input values to the FFT for the second real function. There is then a post processing performed on the FFT results which separate the FFTs of the two functions. Using a similar procedure one can perform a transform on 2N real samples using an N complex sample transform.

The procedure involves alternating the real sample values between the real and imaginary inputs to the FFT. If, as in our example, the input to the FFT is a 2 by 32 array containing the complex values for 32 inputs, the 64 real samples would be loaded into it as follows:

N	00 01 02 03 04 05 06 07 30 31
REAL	00 02 04 06 08 10 12 14 60 62
IMAGINARY	01 03 05 07 09 11 13 15 61 63

This procedure is referred to as a pre-weave. In order to derive the desired results, the FFT is run, and then a post-weave operation is performed. The formula for the post-weave is shown below:

$$\begin{aligned}
 X_r(n) &= \left[\frac{R(n)}{2} + \frac{R(N-n)}{2} \right] + \cos \frac{\pi n}{N} \left[\frac{I(N)}{2} + \frac{I(N-n)}{2} \right] - \\
 &\quad \sin \frac{\pi n}{N} \left[\frac{R(n)}{2} - \frac{R(N-n)}{2} \right] \quad n = 0, 1, \dots, N-1 \\
 X_i(n) &= \left[\frac{I(n)}{2} - \frac{I(N-n)}{2} \right] - \sin \frac{\pi n}{N} \left[\frac{I(n)}{2} + \frac{I(N-n)}{2} \right] - \\
 &\quad \cos \frac{\pi n}{N} \left[\frac{R(n)}{2} - \frac{R(N-n)}{2} \right] \quad n = 0, 1, \dots, N-1 \quad (11)
 \end{aligned}$$

Where R(n) is the real FFT output value

I(n) is the imaginary FFT output value

Xr(n) is the real post-weave output

Xi(n) is the imaginary post-weave output

Note that the output is now one-sided instead of mirrored around the center frequency as it is in Figure 5. The magnitude of the signal at each frequency is calculated by taking the square root of the sum of the squares. The magnitude can now be plotted against frequency, where the frequency steps are defined as:

$$\frac{n}{NT} \quad n = 0, 1, 2, 3, \dots, N-1$$

Where N is the number of complex samples (ie. 32 in this case) T is the time between samples

A value of zero on the frequency scale corresponds to the DC component of the waveform. Most signal analysis is done using Decibels (dB), the conversion is dB = 10 LOG (Magnitude squared). Decibels are not used as an absolute measure, instead signals are compared by the difference in decibels. If the ratio between two signals is 1:2 then there will be a 3 dB difference in their power.

5.0 USING THE FFT

There are several things to be aware of when using FFTs, but with the proper cautions, the FFT output can be used just like that of a spectrum analyzer. The

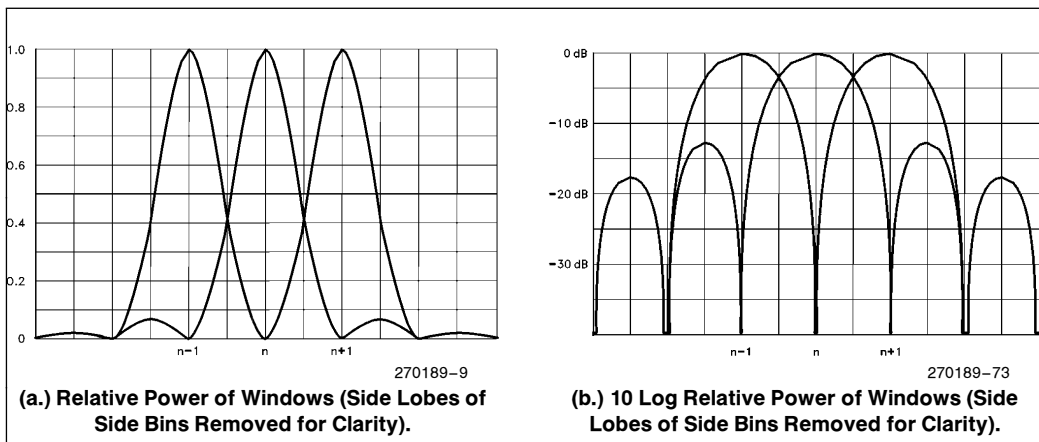


Figure 6. Bin Windows

first precaution is that the FFT is a discrete approximation to a continuous Fourier Transform, so the output will seldom fit the theoretical values exactly, but it will be very close.

Since the programs in this application note generate a one-sided transform with $N=32$, the frequency granularity is fairly coarse. Each of the frequency components output from the FFT is actually the sum of all energy within a narrow band centered on that frequency. This band of sensitivity is referred to as a “bin”. The reported magnitude is the actual magnitude multiplied by the value of the bin window at the actual frequency. Figure 6 shows several bin windows. Note that these windows overlap, so that a frequency midway between the two center frequencies will be reported as energy split between both windows. Be careful not to

confuse the *sampling window* NT with *bin windows* or with the *windowing function*.

Another area of caution is the relationship of the sampling window to the frequency of the waveform. For the best accuracy, the window should cover an exact multiple of the period of the waveform being analyzed. If it covers less than one period, the results will be invalid. Other variations from ideal will not produce invalid results, just additional noise in the output.

If the sampling window does not cover an exact multiple of all of the frequency components of a waveform, the FFT results will be noisy. The reason for this is the sharp edge that the FFT sees when the edges of the window cut off the input waveform. Figure 7 shows a waveform that is an exact multiple of the window and

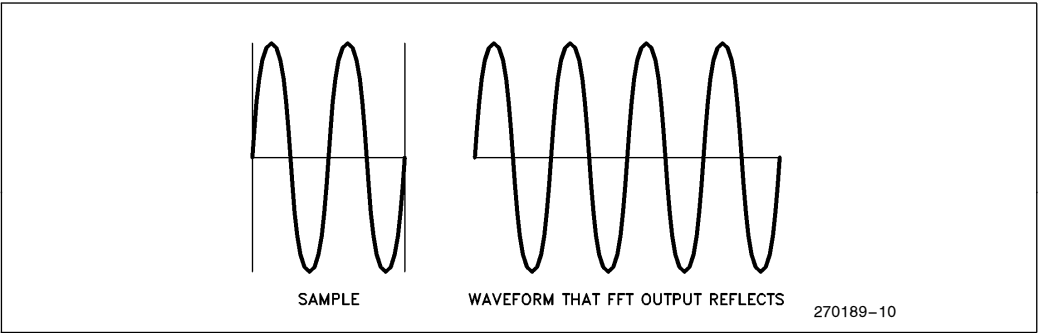


Figure 7. Waveform is a Multiple of the Window

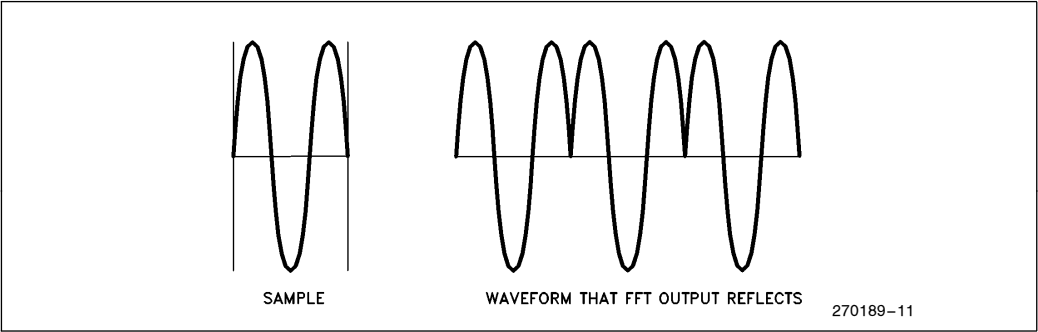


Figure 8. Waveform is Not a Multiple of the Window

the periodic waveform that the FFT output reflects. In Figure 8, the waveform is not a multiple of the window and the waveform that the FFT output reflects has discontinuities. These discontinuities contribute to the noise in an FFT output. This noise is called “spectral leakage”, or simply “leakage”, since it is leakage between one frequency spectrum and another which is caused by digitization of an analog process.

To reduce this leakage, a process called windowing is used. In this procedure the input data is multiplied by specific values before being used in the FFT. The term “windowing” is used because these values act as a window through which the input data passes. If the input window goes smoothly to zero at both endpoints of

the sampling window, there can be no discontinuities. Figure 9 shows a Hanning window and its effect on the input to an FFT. The Hanning window was named after its creator, Julius Von Hann, and is one of the most commonly used windows. More information on windowing and the types of windows can be found in the paper by Harris listed in the bibliography. As expected, the results of the FFT are changed because of the input windowing, but it is in a very predictable way.

Using the Hanning window results in bin windows which are wider and lower in magnitude than normal, as can be seen by comparing Figure 6 with Figure 10. For an input frequency which is equal to the center frequency of a bin window, the attenuation will be 6 dB on the center frequency. Since the bin windows are

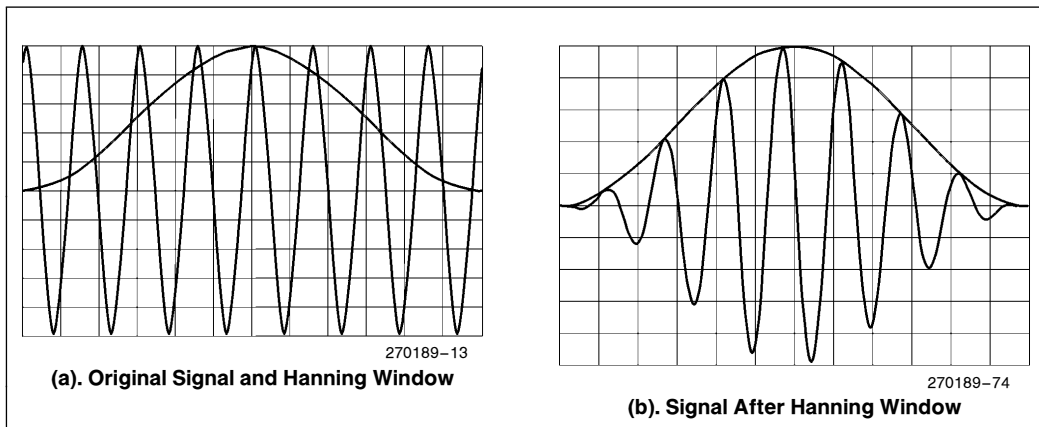


Figure 9. Effect of Hanning Window on FFT Input

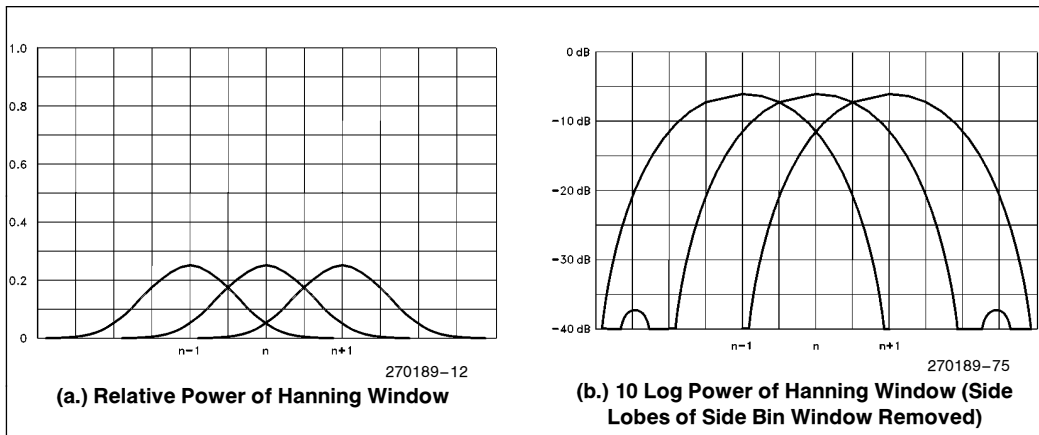


Figure 10. Bin Windows after Using Hanning Input Window

wider than normal, the input frequency will also have energy which falls into the bins on either side of center. These side bins will show a reading of 6 dB below the center window. The disadvantage of this spreading is far less than the advantage of removing leakage from the FFT output.

A set of FFT output plots are included in the Appendix. These plots show the effect of windowing on various signals. There are examples of all of the cases described above. A brief discussion of the plots is also presented.

Applications which can make use of this frequency magnitude information include a wide range of signal processing and detection tasks. Many of these tasks use digital filtering and signature analysis to match signals to a standard. This technique has been applied to anti-knock sensors for automobile engines, object identification for vision systems, cardiac arrhythmia detectors, noise separation and many other applications. The ability to do this on a single-chip computer opens a door to new products which would have not been possible or cost effective previously.

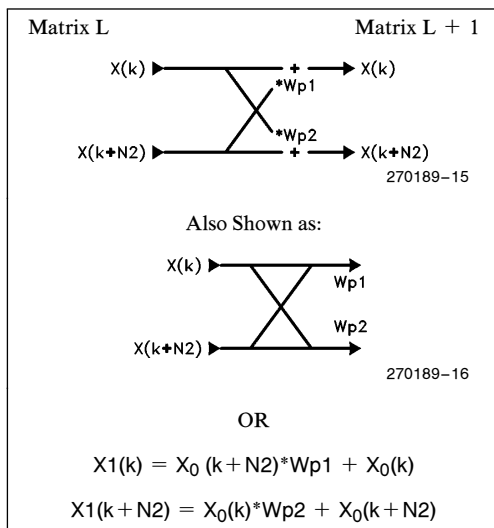
The next four sections of this application note cover the operation of the programs on a line by line basis. Section 6 shows an implementation of the FFT algorithm in BASIC. This code is used as a template to write the ASM96 code in Section 7. Sections 8, 9, and 10 cover the code sections which support the FFT module. After all of the code sections are discussed, an overview of how to use the program is presented in Section 11.

6.0 BASIC PROGRAM FOR FFTS

The algorithm for this FFT is shown in the flowchart in Figure 11 and the BASIC program in Listing 1. There are four sections to this program: initialization, pre-weaving, transform calculation, and post-weaving. The flowchart is generalized, however, the BASIC program has been optimized for assembly language conversion with 64 real samples.

On the flowchart, the initialization and pre-weaving sections are incorporated as "Read in Data". The data to be read includes the raw data as well as the size of the array and the scaling factor. The details for pre-weaving have been discussed earlier, and initialization varies from computer to computer. LOOP COUNT keeps track of which of the factored matrices are being multiplied. SHIFT is the shift count which is used to determine the power of W (as defined earlier) which will be used in the loop.

For each loop N calculations are performed in sets of two. Each calculation set is referred to as a butterfly and has the following form:

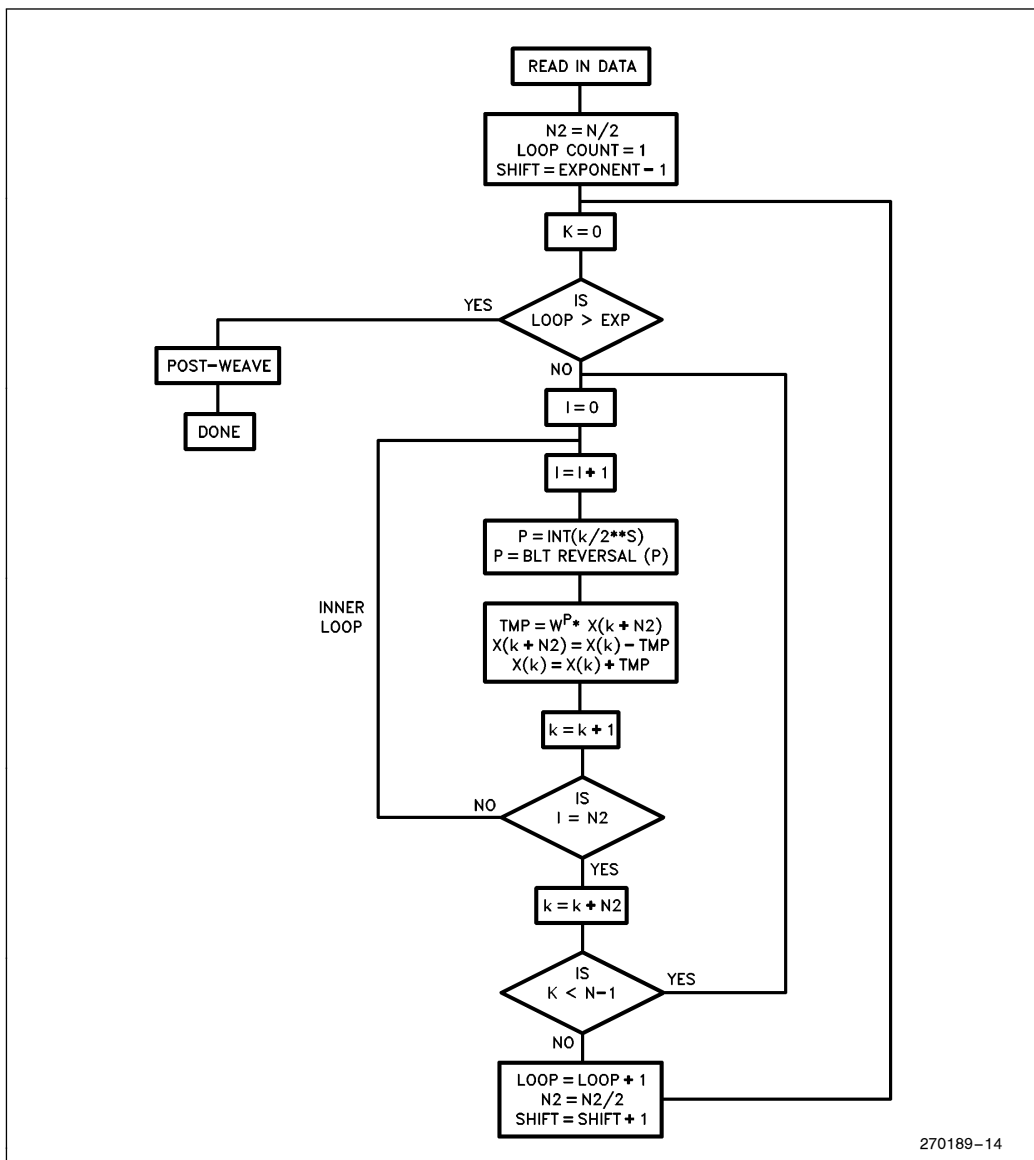


In general, the W factors are not the same. However, for the case of this FFT algorithm, Wp1 will always equal $(-Wp2)$. This is because of the way in which "p" is calculated, and the fact that W(x) is a sinusoidal function.

The inner loop in the flowchart is performed N2 times. For LOOP=1, N2=N/2 and if INCNT=N2 then $k=N2$ and $k+N2=N$, so the first loop is done and parameters LOOP, N2, and SHIFT are updated. For the first loop, all N/2 sets of calculations are performed contiguously. As LOOP increases, the number of contiguous calculations are cut in half, until LOOP=EXPONENT.

When LOOP=EXPONENT, N2=1, the butterfly is then performed on adjacent variables. Figure 12 shows the butterfly arrangement for a calculation where N=8, so that EXPONENT=3.

The BASIC program follows this flowchart, but operations have been grouped to make it easier to convert it to assembly language. Also not shown in the flowchart are several divide by 2 operations. There are five in the main section, one per loop. These provide the T/NT factor in equation 8 for $N=32$ ($2^5=32$). There is also an extra divide by two in the post-weave section. It is required to prevent overflows when performing the 16-bit signed arithmetic in the ASM96 program. As a result of these operations, the input scale factor is $\pm 1 = \pm 32767$ and the output scaling is $\pm 1 = \pm 16384$. Note, the maximum input values are ± 0.99997 .



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Figure 11. Flowchart of Basic Program

```

100 ' THIS IS FFT13, FEBRUARY 4, 1986
105 '
110 ' COPYRIGHT INTEL CORPORATION, 1985
115 ' BY IRA HORDEN, MCO APPLICATIONS
120 '
125 ' THIS PROGRAM PERFORMS A FAST FOURIER TRANSFORM ON 64 REAL DATA POINTS
130 ' USING A 2N-POINTS WITH AN N-POINT TRANSFORM ALGORITHM. THE FIRST
135 ' SECTION OF THE PROGRAM PERFORMS A STANDARD TRANSFORM ON DATA THAT HAS
140 ' BEEN INTERLEAVED BETWEEN THE REAL AND IMAGINARY INPUT VALUES. THE
145 ' RESULTS OF THAT TRANSFORM ARE THEN POST-PROCESSED IN THE SECOND SECTION
150 ' OF THE PROGRAM TO PROVIDE THE 32 OUTPUT BUCKETS. THE OUTPUT VALUES ARE
155 ' MULTIPLIED BY "M" TO MAKE IT EASY TO COMPARE WITH THE ASM-96 PROGRAM
160 '
165 INPUT "NAME OF LIST FILE"; LST$
170 PRINT
175 OPEN LST$ FOR OUTPUT AS #1
180 '
200 ' SET UP VARIABLES FOR BASIC
210 DIM XR(32),XI(32),WR(32),WI(32),BR(32)
220 M=16383 ' M=MULT. FACTOR FOR SCALING
230 N=32 : N1=31 : N2=N/2 ' N=NUMBER OF DATA POINTS
240 LOOP=1 : K=0 : EXPONENT=5 : SHIFT=EXPONENT-1 ' 2**E=N
250 PI=3.141592654# : TPN=2*PI/N : PIN=PI/N
260 '
270 ' READ IN CONSTANTS
280 FOR P=0 TO 31 : PN=P*TPN
290 WR(P)=COS(PN) : WI(P)=-SIN(PN) : READ BR(P)
300 NEXT P
310 '
320 FOR K=0 TO 31 ' READ IN DATA
330 READ XR(K) : READ XI(K)
350 NEXT K
360 '
400 ' INITIALIZATION OF LOOP
410 K=0
420 IF LOOP>EXPONENT THEN 700
430 INCNT=0
440 ' ACTUAL CALCULATIONS BEGIN HERE
445 '
450 INCNT=INCNT+1
460 P=BR(INT(K/(2^SHIFT)))
470 WRP=WR(P) : WIP=WI(P) : KN2=K+N2 ' WRP AND WIP ARE CONSTANTS BASED ON
480 TMPR= (WRP*XR(KN2) - WIP*XI(KN2))/2 ' SINES AND COSINES OF BIT REVERSED
490 TMPI= (WRP*XI(KN2) + WIP*XR(KN2))/2 ' VALUES OF K SHIFTED RIGHT S TIMES
500 TMPR1=XR(K)/2 : TMPI1=XI(K)/2
510 XR(K+N2) = TMPR1 - TMPR ' TMPR, TMPI ARE THE REAL AND IMAGINARY
520 XI(K+N2) = TMPI1 - TMPI ' RESULTS OF A COMPLEX MULTIPLICATION
530 XR(K) = TMPR1 + TMPR
540 XI(K) = TMPI1 + TMPI
550 '
560 K=K+1
570 IF INCNT<N2 THEN GOTO 450
580 K=K+N2 ' SINCE THE ARRAY IS PROCESSED 2 POINTS AT A TIME,
590 IF K<N1 THEN GOTO 430 ' ONLY N/2 LOOPS NEED TO BE MADE. ON EACH PASS,
600 LOOP=LOOP+1 : N2=N2/2 ' THE VALUE OF N2 CHANGES AND SMALLER CONSECUTIVE
605 SHIFT=SHIFT-1 ' SECTIONS ARE PROCESSED.
610 GOTO 400
620 '
690 '
691 '
692 '
693 '

```

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Listing 1—BASIC FFT Program


```

694 '
695 '
696 '
697 '
700 ' POST-PROCESSING AND REORDERING BEGIN HERE
710 '
720 FOR K = 0 TO 31
730 KPIN=K*PIN
740 XBRK=XR(BR(K)) : XIBRK=XI(BR(K)) ' CONDENSED FOR EASE OF ASM PROGRAMMING
750 XBRNK=XR(BR(N-K)) : XIBRNK=XI(BR(N-K))
760 TI = (XBRK+XIBRNK)/2
770 TR = (XBRK-XIBRNK)/2
780 XRT= (XBRK+XIBRNK)/4
790 XIT= (XIBRK-XIBRNK)/4
800 OUTR= XRT + TI*COS(KPIN)/2 - TR*SIN(KPIN)/2
810 OUTI= XIT - TI*SIN(KPIN)/2 - TR*COS(KPIN)/2
820 '
830 MAGSQ = OUTR*OUTR+OUTI*OUTI ' THE ASM-96 PROGRAM USES A TABLE LOOK-UP
840 MAG = SQR(MAGSQ) ' ROUTINE TO CALCULATE SQUARE ROOTS
845 IF MAGSQ*M < .5 THEN DECIBEL=0 : GOTO 900
847 DBFACT=M/2/32767*M ' M^2 / 64K
850 DECIBEL=10*LOG(MAGSQ*DBFACT)
860 DECIBEL=DECIBEL * .434294481#
900 GOTO 930
910 PRINT #1, USING "***** "; K,
920 PRINT #1, USING "\ \"; HEX$(M*OUTR), HEX$(M*OUTI), HEX$(M*MAG)
930 ' GOTO 950
942 PRINT #1, USING "## "; K;
943 PRINT #1, USING "##.***** "; OUTR,OUTI,MAG;
945 PRINT #1, USING "###.### "; DECIBEL;
947 PRINT #1, USING "***** "; M*OUTR, M*OUTI, M*MAG
950 NEXT K
960 '
970 IF LST$<>"SCRN:" THEN PRINT #1, CHR$(12)
999 END
1000 END
1010 ' DATA FOR BR(P) - BIT REVERSAL
1020 DATA 0,16,8,24,4,20,12,28,2,18,10,26,6,22,14,30
1030 DATA 1,17,9,25,5,21,13,29,3,19,11,27,7,23,15,31
1040 ' DATA FOR XR,XI
1050 DATA 2,2,2,2,2,2,2,2,2,2,2,2,2,2,2,2
1060 DATA 2,2,2,2,2,2,2,2,2,2,2,2,2,2,2,2
1070 DATA -2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2
1080 DATA -2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2,-2

```

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Listing 1—BASIC FFT Program (Continued)

Lines 165-175 set up the file for printing the data, this can be SCRNI:, LPT1:, or any other file.

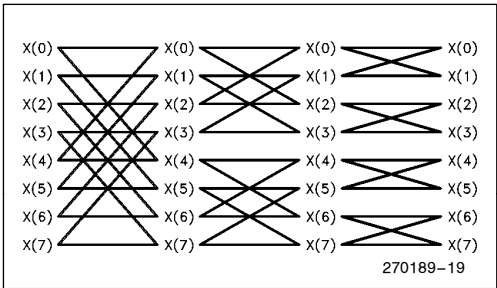


Figure 12. Butterflies with N = 8

Lines 200-310 set up the constants and calculate the WP terms which are stored in the matrices WR(p) and WI(p), for the real and imaginary component respectively.

Lines 320-350 read in the data, alternately placing it into the real and imaginary arrays. The data is scaled by 2 to make the data table simpler.

Lines 410-430 initialize the loop and test for completion.

Lines 450-620 perform the FFT algorithm. Note that all calculations are complex, with the suffixes "R" and "I" indicating real and imaginary components respectively.

The variables on line 470, TMPR1 and TMP11 would normally not be used in a BASIC program as more than one operation can be performed on each line. However, indirect table lookups always use a separate line of assembly code, so separate lines have been used here.

Lines 700-810 perform the post-weave. This is not in the flowchart, but can be found in Equation 11. Once again, table look-ups are separated and additional variables are used for clarity. The variables BR(x) are the bit reversal values of x.

Line 830 calculates the magnitude of the harmonic components.

Lines 900-950 print the results of the calculations, with line 900 determining if the print-out should be in hex or decimal.

Lines 1000-1080 are the data for the bit reversal values and input datapoints. The input waveform is one cycle of a square-wave.

7.0 ASM96 PROGRAM FOR FFTS

The BASIC program just presented has been used as an outline for the ASM96 program shown in Listing 2. There are many advantages to using the BASIC program as a model, the main ones being debugging and testing. Since the BASIC program is so similar in program flow to the ASM96 program, it's possible to stop the ASM96 program at almost any point and verify that the results are correct.

SERIES-III MCS-96 MACRO ASSEMBLER, V1.0

SOURCE FILE: :F2:FFTRUN.A96

OBJECT FILE: :F2:FFTRUN.OBJ

CONTROLS SPECIFIED IN INVOCATION COMMAND: NOSB

```

EER LOC OBJECT      LINE  SOURCE STATEMENT
1  $pagelength(50)
2
3  FFT_RUN MODULE STACKSIZE(6)
4
5  ; Intel Corporation, January 24, 1986
6  ; by Ira Horden, MCO Applications
7
8  ; This module performs a fast fourier transform (FFT) on 64 real data
9  ; points using a 2N-point algorithm. The algorithm involves using a standard
10 ; FFT procedure for 32 real and 32 imaginary numbers. The real and imaginary
11 ; arrays are filled alternately with real data points, and the output of the
12 ; FFT is run through a post-processor. The result is a one sided array with 32
13 ; output buckets. The post processing includes a table lookup algorithm for
14 ; taking the square root of an unsigned 32-bit number.
15
16 ; All of the calculations in the main FFT program are done using 16-bit
17 ; signed integers. The maximum value of any frequency component is therefore
18 ; +/- 32K. (Note that a square wave of +/-32K has a fundamental component
19 ; greater than +/- 40K). Wherever possible tables are used to increase the
20 ; speed of math operations. The complete transform, including obtaining the
21 ; absolute magnitude of each frequency component, executes in 12
22 ; milliseconds with internal variables, 14 ms with external.
23
24 ; The program requires two 32-word input arrays, with the sample values
25 ; alternated between the two. These start at XREAL and XMAG. The resultant
26 ; magnitude will be placed in a 32-word array at FFT_OUT. These are all
27 ; externally defined variables. The external constant SCALE_FACTOR is used to
28 ; divide the output when averaging will be used. Since the program averages
29 ; its output, it is necessary to clear the array based at FFT_OUT before
30 ; calling FFT_CALC to start the program.
31
32 ; The program was originally written in BASIC for testing purposes. The
33 ; comments include these BASIC statements to make it easier to follow the
34 ; algorithm.
35
36
37 $EJECT

```

```

38      RSEG
39      EXTRN portl, zero, error
41
42      OSEG at 24H
43      TMPR: ds1 1 ; Temporary register, Real
44      TMP1: ds1 1 ; Temporary register, Imaginary
45      TMP2: ds1 1 ; Temporary register, Real
46      TMP3: ds1 1 ; Temporary register, Imaginary
47      XTMP: ds1 1 ; Temporary data register, Real
48      XTMP: ds1 1 ; Temporary data register, Imaginary
49      XTRNK: ds1 1
50      XTRNK: ds1 1
51      XTRNK: ds1 1
52      XTRNK: ds1 1
53      diff equ xtrnk :long ; Table difference for square root
54      sqrt equ xtrnk :long ; Square root
55      log equ xtrnk :long ; 10 Log magnitude*2
56      nextloc equ xtrnk :long ; Next location in table
57
58      WIP equ xtrnk :word ; Multiplication factor, Real
59      WIP equ xtrnk+2 :word ; Multiplication factor, Imaginary
60      IN_CNT equ xtrnk-2 :word
61      NDIV2 equ xtrnk :word ; n divided by 2 (0 < n < N) *2
62
63      KPTR: ds1 1 ; K for counter *2 to index words
64      KN2: ds1 1 ; KPTR + NDIV2
65      N_SUB_K: ds1 1 ; N-K *2 to index words
66      RK: ds1 1 ; Bit reversed pointer of KPTR
67      RNK: ds1 1 ; Bit reversed pointer of N_SUB_K
68      SHFT_CNT: ds1 1
69      LOOP_CNT: ds1 1
70      ptr equ kn2 :word ; Pointer for square root table
71
72      DSEG
73
74      EXTRN FFT_MODE ; FFT MODE: mode for FFT input and graphing
75      EXTRN XREAL, XIMAG ; XREAL, XIMAG: Base addresses for 32 16-bit signed
76      EXTRN FFT_OUT ; entries for real and imaginary numbers respectively.
77      EXTRN ; FFT_OUT: Starting address for 32 word array
78      EXTRN ; of magnitude information.
79
79      OUTR: ds1 32 ; Real component of fft
80      OUTI: ds1 32 ; Imaginary component of waveform
81
82      PUBLIC OUTR,OUTI
83
84      $EJECT

```


MCS-96 MACRO ASSEMBLER ERR LOC OBJECT	FFT_RUN LINE	SOURCE STATEMENT	02/18/86	PAGE	4
	128	;; Complex multiplication follows			
22BE F84F4F00003C24	130 ;	tmpr,wpr,xreal[kn2] ;;; 480 TMPR= (WRP*XR(KN2) - WIP*XI(KN2))/2			
22C5 F84F4F00003E28	131 gm:	tmpr,wip,ximag[kn2]			
22CC 682A26	132	mul			
	133	tmpr+2,tmpr+2			
22CF F84F4F00003C2C	134 ;	tmpr,wpr,ximag[kn2] ;;; 490 TMP1= (WRP*XI(KN2) + WIP*XR(KN2))/2			
22D6 F84F4F00003E28	135	mul			
22D0 642E2A	136	tmpr,wip,xreal[kn2]			
	137	tmpr+2,tmpr+2			
	138	add			
	139	;; using the high byte only of a signed multiply			
	140	;; provides an effective divide by two			
22E0 DC55	141	BVT			
	142	ERR1 ; Branch on error in complex multiplications			
22E2 A34D00002C	143	tmpr,xreal[kptr] ;;; 500 TMPRI-XR(K)/2 :			
22E7 0A012C	144	tmpr,#1			
22EA A34D000030	145	ld			
22EF 0A0130	146	tmpr,ximag[kptr]			
	147	tmpr,#1			
	148	shra			
22F2 48282C34	149 ;	xtmp,tmpr,tmpr+2 ;;; 510 XR(KN2) = TMPRI - TMPI			
22F6 C34F000034	150 gr2:	xtmp,xreal[kn2] ;;;			
	151	st			
22FB 482A3038	152 ;	xtmp,tmpr,tmpr+2 ;;; 520 XI(KN2) = TMPRI - TMPI			
22FF C34F000038	153 gr2:	xtmp,ximag[kn2] ;;;			
	154	st			
2304 44282C34	155 ;	xtmp,tmpr,tmpr+2 ;;; 530 XR(K) = TMPRI + TMPI			
2308 C34D000034	156	xtmp,xreal[kptr]			
	157	st			
230D 442A3038	158 ;	xtmp,tmpr,tmpr+2 ;;; 540 XI(K) = TMPRI + TMPI			
2311 C34D000038	159 gr:	xtmp,ximag[kptr]			
	160	st			
2316 DC23	161	BVT			
	162	ERR2 ; Branch on error in complex additions			
	163				
	164	\$eject			

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Listing 2—ASM96 FFT Program (Continued)

```

MCS-96 MACRO ASSEMBLER          02/18/96          PAGE    5
ERR LOC OBJECT                    FFT_RUN
2318 6502004C                      LINE
165 ;                               SOURCE STATEMENT
166 1k: add      kptr,#2             ;;;; 560 K=K+1
167
168 ;                               ;;;;
169 in_cnt,ndiv2                     ;;;; 570 IF INCNT<N2 THEN GOTO 450
170 bit IN_LOOP                     ;;;;
171
172 ;                               ;;;; 580 K=K+N2
173 add      kptr,ndiv2              ;;;;
174 ;                               ;;;; 590 IF K<N1 THEN GOTO 430
175 cmp      kptr,#62                ;;;;
176 bit MID_LOOP                     ;;;;
177
178 incb      loop_cnt                ;;;; 600 LOOP=LOOP+1 : N2=N2/2
179 ndiv2,#1  ;;;; 605 SHIFT=SHIFT+1
180 shra      shift_cnt              ;;;;
181 decb
182 ;                               ;;;; 610 GOTO 400
183 br      OUT_LOOP                ;;;;
184
185 ERR1: ldb      error,#01          ; overflow error, 1st set of calculations
186
187 ret
188 ERR2: ldb      error,#02          ; overflow error, 2nd set of calculations
189
190 ret
191 $EJECT

```

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Listing 2—ASM96 FFT Program (Continued)

MCS-96 MACRO ASSEMBLER	FFT_RUN	LINE	SOURCE STATEMENT	02/18/86	PAGE
ERR LOC OBJECT		192			6
		193	UNWEAVE: ; ; ; ; 700 ' POST-PROCESSING AND REORDERING STARTS HERE		
233F		194	portl,#00000010b ;****		
233F B10200	E	195	ld		
		196	kprr		
		197	n_sub_k,#64 ; ; ; ; 720 FOR K=0 TO 31		
2342 014C		198	clr		
2344 A1400050		199	ld		
2346		200	UN_LOOP:		
		201	;		
2348 A34003862		202	ld rk,brev[kptr]		
234D A35300003C	E	203	ld xrrk,xreal[rk]		
2352 063C		204	ext xrrk		
2354 A353000044	E	205	ld xirk,ximag[rk]		
2359 0644		206	ext xirk		
		207	;		
235B A351003864		208	ld rnk,brev[n_sub_k]		
2360 A355000040	E	209	ld xrrnk,xreal[rnk]		
2365 0640		210	ext xrrnk		
2367 A355000048	E	211	ld xirnk,ximag[rnk]		
236C 0648		212	ext xirnk		
		213	;		
236E 44484428		214	add tmpi,xirk,xirnk		
2372 A04A2A		215	ld tmpi-2,xirnk+2		
2375 A4462A		216	addc tmpi-2,xirnk+2		
2378 0E0128		217	shrl tmpi,#1 ; 16 bit result in tmpi		
		218	;		
237B 48403C24		219	;		
237F A03E26		220	sub tmpi,xrrk,xrrnk		
2382 A84226		221	ld tmpi-2,xrrk+2		
2385 0E0124		222	subc tmpi-2,xrrnk+2		
		223	shrl tmpi,#1 ; 16 bit result in tmpi		
		224	;		
2388 44403C34		225	;		
238C A03E36		226	add xrtmp,xrrk,xrrnk		
238F A44236		227	ld xrtmp-2,xrrk+2		
2392 0D0E34		228	addc xrtmp-2,xrrnk+2		
		229	shll xrtmp,#14 ; 32 bit result in xrtmp		
		230	;		
2395 48484438		231	;		
2399 A0463A		232	sub xitmp,xirk,xirnk		
239C A84A3A		233	ld xitmp-2,xirk+2		
239F 0D0E38		234	subc xitmp-2,xirnk+2		
		235	shll xitmp,#14 ; 32 bit result in xitmp		
		236	;		
		237	\$eject		

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Listing 2—ASM96 FFT Program (Continued)

MCS-96 MACRO ASSEMBLER	FFT_FUN	LINE	SOURCE STATEMENT	02/18/86	PAGE	7
		238	;			
		239	;;;;			
		240	;			
		241	mr:			
		242	mul tmp1,tmp,sinfn[kptr]			
		243	mul tmp1,tmp,cosfn[kptr]			
		244	add xrtmp,tmp1			
		245	addc xrtmp+2,tmp1+2			
		246	sub xrtmp,tmp1			
		247	subc xrtmp+2,tmp1+2			
		248	st xrtmp+2,out1[kptr]			
		249	st			
		250	;			
		251	;;;;			
		252	810 OUTI= (XIT - TI*SINFN(K)/2 - TRACOSFN(K)/2)			
		253	mi:			
		254	mul tmp1,tmp,cosfn[kptr]			
		255	sub tmp1,tmp1			
		256	subc xrtmp,tmp1			
		257	subc xrtmp+2,tmp1+2			
		258	sub xrtmp,tmp1			
		259	subc xrtmp+2,tmp1+2			
		260	st xrtmp+2,out1[kptr]			
		261	st			
		262	;;;;			
		263	830 MAG =SQR(OUTR*OUTR + OUTI*OUTI)			
		264	GET_MAG:			
		265	ld tmp1,xrtmp+2			
		266	ld tmp1,xrtmp+2			
		267	;			
		268	mul tmp1,tmp1			
		269	mul tmp1,tmp1			
		270	add tmp1,tmp1			
		271	addc tmp1+2,tmp1+2			
		272	;			
		273	fft_mode,2,CALC_SORT			
		274	bbcc			
		275	\$reject			
		2380				
		2380	A03624			
		2383	A03A28			
		2386	F86C2424			
		238A	F86C2828			
		238E	642824			
		23F1	A42A26			
		23F4	32004C			

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Listing 2—ASM96 FFT Program (Continued)

MCS-96 MACRO ASSEMBLER	FFT_RUN	SOURCE STATEMENT	02/18/86	PAGE 8
ERR LOC OBJECT	LINE			
	276	;;;; *** CALCULATE 10 log magnitude^2 ***		
	277	; Output = 512*10*LOG(x) x=1,2,3 ... 64K		
	278			
	279	CALC LOG:		
23FF	280	clr shift_cnt		
23FF 0156	281	tmpr,shift_cnt ; Normalize and get normalization factor		
23FF 0F5624	282	normal shift_cnt,#15		
23FC 990F56	283	cmpb LOG_IN_RANGE ; Jump if SHIFT_CNT <= 15		
23FF DA04	284	jle		
	285	clr log		
2401 0140	286	br LOG_STORE		
2403 202C	287			
	288			
2405	289	LOG_IN_RANGE:		
2405 44565656	290	add shift_cnt,shift_cnt,shift_cnt ; Make shift_cnt a pointer		
	291			
2409 AC274E	292	ldbze ptr,tmp+3 ; Most significant byte is table pointer		
240C 444E4E4E	293	add ptr,ptr,ptr ;		
2410 65083A4E	294	add ptr,# LOG_TABLE-256 ; ptr= Table + offset (offset=tmp+3)		
	295	; Use -256 since tmp+3 is always >= 128		
2414 A24F40	296	ld log,[ptr]+		
2417 A24E44	297	ld nxtloc,[ptr] ; Linear Interpolation		
	298			
241A 684044	299	sub nxtloc,log ; nxtloc = next log - log		
241D AC263C	300	ldbze diff,tmp+2 ; diff+1 = nxtloc * tmp+2 / 256		
2420 6C443C	301	mulu diff,nxtloc		
	302			
2423 0C083C	303	shr diff,#8 ; log = log + diff/256		
2426 643C40	304	add log,diff		
2429 080540	305	shr log,#5 ; 8192/32 * 20LOG(x) = 256 * 20LOG(x)		
	306			
242C A7570A3C40	307	addc log,log_offset[shift_cnt] ; add log of normalization factor		
	308			
	309			
	310	:: Log (M*N) = Log M + Log N		
	311			
	312	LOG_STORE:		
2431	313	log,\$SCALE_FACTOR		
2431 080040	314	shr log,zero ; Divide to prevent overflow during		
2434 A40040	315	addc log,FFT_OUT[kptr] ; averaging of outputs		
2437 674D000040	316	add st		
243C C34D000040	317	log,FFT_OUT[kptr]		
	318	BR		
2441 2045	319	ENDL		
		\$eject		

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MCS-96 MACRO ASSEMBLER			FFT_RUN	SOURCE STATEMENT			02/18/86	PAGE	10
ERR	LOC	OBJECT	LINE	;	list	CSEG AT 3800H	Use 2k for tables		
	3800		367						
	3800		368						
	3800		369						
	3800		370	BREV:	;	2*bit reversal value			
	3800	0000200010003000	371						
	3810	0400240014003400	372	DCW		240, 2*16, 2*8, 2*24, 2*4, 2*20, 2*12, 2*28			
	3820	0200220012003200	373	DCW		242, 2*18, 2*10, 2*26, 2*6, 2*22, 2*14, 2*30			
	3830	0600260016003600	374	DCW		241, 2*17, 2*9, 2*25, 2*5, 2*21, 2*13, 2*29			
	3840		375	DCW		243, 2*19, 2*11, 2*27, 2*7, 2*23, 2*15, 2*31			
	3840		376						
	3840	0000800CF9182825	377	SINFN:					
	3850	025A1F62606A270	378	DCW		0, 3212, 6393, 9512, 12539, 15446, 18204, 20787			
	3860	00007F617F807C7A	379	DCW		23170, 25329, 27245, 28898, 30273, 31356, 32137, 32609			
	3870	00007F617F807C7A	380	DCW		32767, 32609, 32137, 31356, 30273, 28898, 27245, 25329			
	3880	00007F617F807C7A	381	DCW		23170, 20787, 18204, 15446, 12539, 9512, 6393, 3212			
	3890	00007F617F807C7A	382	DCW		0, -3212, -6393, -9512, -12539, -15446, -18204, -20787			
	3900	00007F617F807C7A	383	DCW		-23170, -25329, -27245, -28898, -30273, -31356, -32137, -32609			
	3910	00007F617F807C7A	384	DCW		-32767, -32609, -32137, -31356, -30273, -28898, -27245, -25329			
	3920	0000800CF9182825	385	DCW		-23170, -20787, -18204, -15446, -12539, -9512, -6393, -3212			
	3930	0000800CF9182825	386	DCW		0, 3212, 6393, 9512, 12539, 15446, 18204, 20787			
	3940	0000800CF9182825	387	DCW		23170, 25329, 27245, 28898, 30273, 31356, 32137, 32609			
	3942	FF7F	388						
	3942	FF7F	389	COSFN:					
	3952	FF7F617F807C7A	390	DCW		32767, 32609, 32137, 31356, 30273, 28898, 27245, 25329			
	3962	000043351C47653C	391	DCW		23170, 20787, 18204, 15446, 12539, 9512, 6393, 3212			
	3972	000043351C47653C	392	DCW		0, -3212, -6393, -9512, -12539, -15446, -18204, -20787			
	3982	000043351C47653C	393	DCW		-23170, -25329, -27245, -28898, -30273, -31356, -32137, -32609			
	3992	01609F6077626485	394	DCW		-32767, -32609, -32137, -31356, -30273, -28898, -27245, -25329			
	3992	01609F6077626485	395	DCW		-23170, -20787, -18204, -15446, -12539, -9512, -6393, -3212			
	3992	0000800CF9182825	396	DCW		0, 3212, 6393, 9512, 12539, 15446, 18204, 20787			
	3992	0000800CF9182825	397	DCW		23170, 25329, 27245, 28898, 30273, 31356, 32137, 32609			
	3992	0000800CF9182825	398						
	3994	FF7F617F807C7A	399	MR:		MR = COS(K*2PI/N)			
	3994	FF7F617F807C7A	400	DCW		32767, 32609, 32137, 31356, 30273, 28898, 27245, 25329			
	3994	000007705CF84B8	401	DCW		23170, 20787, 18204, 15446, 12539, 9512, 6393, 3212			
	3994	016077626F695395	402	DCW		0, -6393, -12539, -18204, -23170, -27245, -30273, -32137			
	3994	0000F918F301C47	403	DCW		-32767, -32609, -32137, -31356, -30273, -28898, -27245, -25329			
	3994	FF7F617F807C7A	404	DCW		0, 6393, 12539, 18204, 23170, 27245, 30273, 32137			
	3994	FF7F	405						
	3996		406	WI:		WI = -SIN(K*2PI/N)			
	3996	000007705CF84B8	407	DCW		-6393, -12539, -18204, -23170, -27245, -30273, -32137			
	3996	016077626F695395	408	DCW		-32767, -32609, -32137, -31356, -30273, -28898, -27245, -25329			
	3996	0000F918F301C47	409	DCW		0, 6393, 12539, 18204, 23170, 27245, 30273, 32137			
	3996	FF7F617F807C7A	410	DCW		32767, 32609, 32137, 31356, 30273, 28898, 27245, 25329			
	3996	FF7F	411	DCW					
	3996	0000	412	\$eject					

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MCS-96 MACRO ASSEMBLER	FFT_RUN	LINE	SOURCE STATEMENT	02/18/86	PAGE	11
ERR LOC OBJECT		413				
33C8		414				
		415	TAB_SQR: ; 65535/(square root of 2**SHIFT_CNT) ; 0<=SHIFT_CNT<32			
		416	:: 1 2 4 8 16 32 64 128			
33C8	FFFF04B50080825A	417	DCW 66535, 46340, 32768, 23170, 16384, 11585, 8192, 5793			
		418				
		419	:: 256 512 1024 2048 4096 8192 16384 32768			
		420	DCW 4096, 2896, 2048, 1448, 1024, 724, 512, 362			
		421				
		422	:: 65536, 131072, 262144, 524288, ...			
		423	DCW 256, 181, 128, 91, 64, 45, 32, 23			
		424	DCW 16, 11, 8, 6, 4, 3, 2, 1			
		425				
		426				
		427	SQ_TABLE: ; square root of n * 2**24 N=128, 129, 130 ... 255			
3A08		428				
		429	DCW 46341, 46522, 46702, 46881, 47059, 47237, 47415, 47591			
		430	DCW 47767, 47942, 48117, 48291, 48465, 48637, 48809, 48981			
		431	DCW 49152, 49322, 49492, 49661, 49830, 49998, 50166, 50332			
		432	DCW 50499, 50665, 50830, 50995, 51159, 51323, 51486, 51649			
		433	DCW 51811, 51972, 52134, 52294, 52454, 52614, 52773, 52932			
		434	DCW 53090, 53248, 53405, 53562, 53719, 53874, 54030, 54185			
		435	DCW 54340, 54494, 54647, 54801, 54954, 55106, 55258, 55410			
		436	DCW 55661, 55712, 55862, 56012, 56162, 56311, 56459, 56608			
		437	DCW 56756, 56903, 57051, 57196, 57344, 57490, 57636, 57781			
		438	DCW 57926, 58071, 58215, 58359, 58503, 58646, 58789, 58931			
		439	DCW 59073, 59215, 59357, 59498, 59639, 59779, 59919, 60059			
		440	DCW 60199, 60338, 60477, 60615, 60754, 60891, 61029, 61166			
		441	DCW 61303, 61440, 61576, 61712, 61848, 61984, 62119, 62254			
		442	DCW 62388, 62523, 62657, 62790, 62924, 63057, 63190, 63323			
		443	DCW 63455, 63587, 63719, 63850, 63982, 64113, 64243, 64374			
		444	DCW 64504, 64634, 64763, 64893, 65022, 65151, 65280, 65408			
		445				
		446				
		447	\$eject			

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FFT_RUN

MCS-96 MACRO ASSEMBLER

ERR LOC OBJECT

LINE

SOURCE STATEMENT

```

3B08      LOG_TABLE:  ; 16394*10*LOG(n/128)      n=128,129,130 ... 256
448      DCW          0, 554, 1103, 1648, 2190, 2727, 3260, 3789
449      DCW          4314, 4835, 5353, 5866, 6376, 6883, 7386, 7885
450      DCW          8381, 8873, 9362, 9848, 10330, 10810, 11286, 11758
451      DCW          12228, 12695, 13158, 13619, 14076, 14531, 14983, 15432
452      DCW          15878, 16321, 16762, 17200, 17635, 18067, 18497, 18925
453      DCW          19349, 19772, 20191, 20609, 21024, 21436, 21846, 22254
454      DCW          22660, 23063, 23464, 23862, 24259, 24653, 25045, 25435
455      DCW          25822, 26208, 26592, 26973, 27353, 27730, 28106, 28479
456      DCW          28851, 29220, 29588, 29954, 30318, 30680, 31040, 31399
457      DCW          31755, 32110, 32463, 32815, 33166, 33512, 33859, 34203
458      DCW          34546, 34887, 35227, 35565, 35902, 36236, 36570, 36901
459      DCW          37232, 37560, 37887, 38213, 38537, 38860, 39181, 39501
460      DCW          39819, 40136, 40452, 40766, 41079, 41390, 41700, 42009
461      DCW          42316, 42622, 42927, 43230, 43533, 43833, 44133, 44431
462      DCW          44729, 45024, 45319, 45612, 45905, 46196, 46486, 46774
463      DCW          47062, 47348, 47633, 47917, 48200, 48482, 48763, 49042
464      DCW          49321
465      LOC_OFFSET:  ; 512*10*LOG(2**(15-n))      n= 0,1,2,3 ... 15
466      DCW          ; 512*10*LOG(0.5)              n= 16,17,18 ... 31
467      DCW          23119, 21578, 20037, 18495, 16954, 15413, 13871, 12330
468      DCW          10789, 9248, 7706, 6165, 4624, 3083, 1541, 0
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ASSEMBLY COMPLETED, NO ERROR(S) FOUND.

270189-44

The BASIC program is used as comments in the ASM96 program. Some of the variables in the ASM96 program have slightly different names than their counterparts in the BASIC program. This was to make the comments fit into the ASM96 code. Highlights in this section of code are a table driven square root routine and log conversion routine which can easily be adapted for use by any program.

Both the square root routine and the log conversion routine use the 32-bit value in the variable TMPR. The square root routine calculates the square root of that value in the variable SQRT+2, a 16-bit variable. In this program, the square root value is averaged and stored in a table.

The log conversion routine divides the value in TMPR by 65536 (2^{16}) and uses table lookup to provide the common log. The result is a 16-bit number with the value $512 * 10 \text{ Log}(\text{TMPR}/65536)$ stored in the variable LOG. This calculation is used to present the results of the FFT in decibels instead of magnitude. With an input of 63095, the output is $512 * 48 \text{ dB}$. The graph program, (Section 10), prints the output value of the plot as INPUT/512 dB.

The following descriptions of the ASM code point out some of the highlights and not-so-obvious coding:

Lines 1-104 initialize the code and declare variables. The input and output arrays of the program are declared external. Note that many of the registers are

overlayable, use caution when implementing this routine with others with overlayable registers.

Lines 116-124 calculate the power of W to be used. Note that KPTR is always incremented by 2. The multiple right shift followed by the AND mask creates an even address and the indirect look to the BR (Bit Reversal) table quickly calculates the power PWR.

Lines 130-138 perform the complex multiplications. Since WIP and WRP range from -32767 to $+32767$, the multiplication is easy to handle. The automatic divide by two which occurs when using the upper word only of the 32-bit result is a feature in this case.

Lines 144-163 use right shifts for a fast divide, then add or subtract the desired variables and store them in the array. Note that the upper word of TMPR and TMPI is used, and the same array is used for both the input and output of the operations.

Lines 165-189 update the loop variables and then check for errors on the complex multiplications and additions. If there are no overflows at this time the data will run smoothly through the rest of the program.

Lines 200-212 load variables with values based on the bit reversed values of pointers.

Lines 214-236 perform additions and subtractions to prepare for the next set of formulas. Note that XITMP and XRTMP are 32-bit values.

Lines 240-260 perform multiplies and summations resulting in 32-bit variables. This saves a bit or two of accuracy. The upper words are then stored as the results.

Lines 263-272 generate the squared magnitude of the harmonic component as a 32-bit value.

Lines 278-310 calculate $10 \log(\text{TMPR}/65536)$. The 32-bit register TMPR is divided by 65536 so that the output range would be reasonable.

First, the number is normalized. (It is shifted left until a 1 is in the most significant bit, the number of shifts required is placed in SHFT_CNT.) If it had to be shifted more than 15 times the output is set to zero.

Next, the most significant BYTE is used as a reference for the look-up table, providing a 16-bit result. The next most significant BYTE is then used to perform linear interpolation between the referenced table value and the one above it. The interpolated value is added to the directly referenced one.

The 16-bit result of this table look-up and interpolation is then added to the Log of the normalization factor, which is also stored in a table. This table look-up approach works fast and only uses 290 bytes of table space.

Lines 321-357 calculate the square root of the 32-bit register TMPR using a table look-up approach.

First, the number is normalized. Next, the most significant BYTE is used as a reference for the look-up table, providing a 16-bit result. The next most significant BYTE is then used to perform linear interpolation between the referenced table value and the one above it. The interpolated value is added to the directly referenced one.

The 16-bit result of this table look-up and interpolation is then divided by the square root of the normalization factor, which is also stored in a table. This table look-up approach works fast and only uses 320 bytes of table space. The results are valid to near 14-bits, more than enough for the FFT algorithm.

Lines 352-360 average the magnitude value, if multiple passes are being performed, and then store the value in the array. The loop-counters are incremented and the process repeats itself.

This concludes the FFT routine. In order to use it, it must be called from a main program. The details for calling this routine are covered in the next section.

8.0 BACKGROUND CONTROL PROGRAM

The main routine is shown in Listing 3. It begins with declarations that can be used in almost any program. Note that these are similar, but not identical, to other 8096 include files that have been published. Comments on controlling the Analog to Digital converter routine follow the declarations.


```

ERR LOC OBJECT      LINE  SOURCE STATEMENT
1  $pagelength(50)
2
3  FFT_MAIN_APNOTE MODULE MAIN, STACKSIZE(6)
4
5  ; Intel Corporation, January 24, 1986
6  ; by Ira Horden, MCO Applications
7
8  ; This program performs an FFT on real data and plots it on a printer.
9  ; it uses the program modules A2DOON, PLOTSP, and FFTRUN. The adjustable
10 ; parameters of each of the programs are set by this main module.
11
12
13
14 $INCLUDE (:F0:DEMO96.INC) ; Include SFR definitions
15 $nolist ; Turn listing off for include file
16
17 *****
18 ;
19 ; Copyright 1985, Intel Corporation
20 ; October 28, 1985
21 ; by Ira Horden, MCO Applications
22
23 ; DEMO96.INC - DEFINITION OF SYMBOLIC NAMES FOR THE I/O REGISTERS OF THE 8096
24 ; *****
25
26 ;
27 ; EQU 00h:WORD ; R/W Zero Register
28 ; EQU 02h:BYTE ; W A to D command register
29 ; EQU 02h:BYTE ; R Low byte of result and channel
30 ; EQU 03h:BYTE ; R High byte of result
31 ; EQU 03h:BYTE ; W Controls HSI transition detector
32 ; EQU 04h:WORD ; W HSI time tag
33 ; EQU 04h:WORD ; R HSO time tag
34 ; EQU 06h:BYTE ; W HSO command tag
35 ; EQU 06h:BYTE ; R HSI status register (reads fifo)
36 ; EQU 07h:BYTE ; R/W Serial port buffer
37 ; EQU 08h:BYTE ; R/W Interrupt mask register
38 ; EQU 09h:BYTE ; R/W Interrupt pending register
39 ; EQU 11h:BYTE ; W Serial port control register
40 ; EQU 11h:BYTE ; R Serial port status register
41 ; EQU 0Ah:BYTE ; W Watchdog timer

```

Listing 3—Main Routine

```

LINE SOURCE STATEMENT
42 TIMER1 EQU 0AH:WORD ; R Timer1 register
43 TIMER2 EQU 0CH:WORD ; R Timer2 register
44 PORT0 EQU 0EH:BYTE ; R I/O port 0
45 BAUD_REG EQU 0FH:BYTE ; W Baud rate register
46 PORT1 EQU 0FH:BYTE ; R/W I/O port 1
47 PORT2 EQU 10H:BYTE ; R/W I/O port 2
48 LOC0 EQU 10H:BYTE ; W I/O control register 0
49 LOC8 EQU 10H:BYTE ; R I/O status register 0
50 LOC1 EQU 10H:BYTE ; W I/O control register 1
51 LOC5 EQU 10H:BYTE ; R I/O status register 1
52 PWM_CONTROL EQU 17H:BYTE ; W PWM control register
53 SP EQU 18H:WORD ; R/W System stack pointer
54 CR EQU 0DH
55 LF EQU 0AH
56
57 PUBLIC ZERO,AD_COMMAND,AD_RESULT_LO,AD_RESULT_HI,HSI_MODE,HSO_TIME,HSI_TIME
58 PUBLIC HSO_COMMAND
59 PUBLIC HSI_STATUS,SEUP,INT_MASK,INT_PENDING,WATCHDOG,TIMER1,TIMER2
60 PUBLIC BAUD_REG,PORT0,PORT1,PORT2,SPSTAT,SPCON,I/OCL,I/OCL1,I/OCL2,I/OCL3
61 PUBLIC PWM_CONTROL,SP,CR,LF
62
63 BSEG at 1CH
64
65 AX: DSW 1 ; Temp registers used in conformance
66 DX: DSW 1 ; with PIM-96(tm) conventions.
67 BX: DSW 1
68 CX: DSW 1
69
70 AL EQU AX :BYTE
71 AH EQU (AX+1) :BYTE
72 BL EQU BX :BYTE
73
74 public ax, bx, cx, dx, ax, ah, bl
75
76 $list ; Turn listing back on
77 ; End of include file
78
79 ; A2D UTILITY COMMANDS/RESPONSES FOR "CONTROL_A2D"
80
81 busy equ 7
82 con_b0 equ 00010000b;convert to BUFF0
83 dump_b0_p_s equ 000101000b; download BUFF0 as PAIRED SIGNED data
84
85
86
87 AVE_NUM equ 1 ; Number of times to average the waveform
88 ; AVR_NUM < 256

```

```

MCS-96 MACRO ASSEMBLER      FFT_MAIN_APNOTE
ERR LOC OBJECT              LINE  SOURCE STATEMENT
0000                        89  SCALE_FACTOR equ 0 ; Number of rights shifts performed on
                               90                               ; output of FFT. Used to prevent overflow
                               91                               ; on summation
                               92
0100                        93  PLOT_RES equ 256 ; Number of input units per plot unit
0080                        94  PLOT_RES_2 equ PLOT_RES/2
9100                        95  PLOT_MAX equ PLOT_RES*145 ; 145 chrs/row
                               96
                               97  PUBLIC scale_factor, plot_res, plot_res_2, plot_max
                               98
                               99
0024                        100  OSEG at 24H ; common oseg area
                               101
0024                        102  tmpreal: ds1 1
0028                        103  tmpimag: ds1 1
002C                        104  wndptr: ds1 1
002E                        105  varptr: ds1 1
                               106
0000                        107  RSEG
0000                        108  fft_mode: dsb 1
0001                        109  error: dsb 1
0002                        110  avf_cnt: dsb 1
                               111
                               112  PUBLIC error, fft_mode
                               113
                               114  EXTRN sample_period, control_a2d
                               115
                               116
0080                        117  DSEG at 80h
0080                        118  XREAL: ; For FFT routine
                               119  DEST_BUFF_BASE: DSW 64 ; For A2D routine
00C0                        120  XIMAG equ XREAL+64 ; For FFT routine
                               121
                               122  PUBLIC DEST_BUFF_BASE, XREAL, XIMAG
                               123
                               124
0200                        125  DSEG AT 200H
                               126
                               127  PLOT_IN: ; For FFT routine
0200                        128  FFT_OUT: DSW 32 ; For FFT routine
0240                        129  BUFFO_BASE: DSW 64 ; For A2D routine
02C0                        130  BUFFI_BASE: DSW 64 ; For A2D routine
                               131
                               132  PUBLIC BUFFO_BASE, BUFFI_BASE, FFT_OUT, PLOT_IN
                               133  $reject

```

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Listing 3—Main Routine (Continued)

MCS-96 MACRO ASSEMBLER	FFT_MAIN_APNOTE	02/18/86	PAGE	4
ERR LOC OBJECT	LINE	SOURCE STATEMENT		
2080	134	CSEG AT 2080H		
	135			
	136			
	137	EXTEN INIT_OUTPUT, DRAW_GRAPH, CON_OUT		; For Plot Routine
	138	EXTEN FFT_CALC		; For FFT routine
	139	EXTEN A2D_BUFF_UTIL		; For A2D routine
	140			
	141	ID SP,#STACK		
	142	LD AX,3000H		
	143	SBE_WAIT:		
	144	djnz al,sbe_wait		; WAIT FOR SBE TO CLEAR SERIAL PORT INTERRUPTS
	145	djnz ah,sbe_wait		
	146			
	147	BEGIN: CALL INIT_OUTPUT		; Initialize serial port
	148			
	149	NEW_TRANSFORM_SET:		
	150	ldb fft_mode,#0000B		; Bit 0 - Real data / Tabled data#
	151			; Bit 1 - Windowed / Unwindowed#
	152			; Bit 2 - 10log Mag^2 / Magnitude#
	153			; Bit 3 - 256*db Plot / Normal Plot#
	154	ldi avr_cnt,#avr_num		
	155	clr bx		; clear fft magnitude array
	156	CLRRAM: st zero,fft_out[bx]		
	157	add bx,#2		
	158	cmp bx,#64		
	159	bit CLRRAM		
	160			
	161	C_load: bnc		
	162	CALL LOAD_DATA		; Branch if real data is not used
	163	br		
	164			
	165	do_tab: CALL TABLE_LOAD		
	166			
	167	C_win: bnc		
	168	CALL DO_WINDOW		; Branch if windowing is not used
	169			
	170	CALC: CALL FFT_CALC		
	171	errtrp: cmpb error,zero		
	172	jne errtrp		
	173			
	174	DJNZ avr_cnt, LOAD_DATA		; repeat for AVR_NUM counts
	175			
	176	CALL DRAW_GRAPH		
	177			
	178	BR NEW_TRANSFORM_SET		
	179	\$eject		

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Listing 3—Main Routine (Continued)

ERR	LOC	MACRO ASSEMBLER	FFT_MAIN_APNOTE	SOURCE STATEMENT	02/18/86	PAGE	6
	2182	012C		DO_WINDOW:			
	2182	012C		clr wndptr			
	2184	012E		varptr			
	2186			WINDOW:			
	2186	A32BE211C		ld ax,hanning[wndptr]			
	2188	A32DCU2120		bx,hanning*2[wndptr]			
	2190	FE4F2F0001C24		tmpreal,ax,xreal[varptr]			
	2197	FE4F2F0002028		tmpimag,bx,ximag[varptr]			
	2198	000124		tmpreal,#1			
	21A1	000128		tmpimag,#1			
	21A4	C32F800026		tmpreal*2,xreal[varptr]			
	21A9	C32FC0002A		tmpimag*2,ximag[varptr]			
	21AB	6004002C		wndptr,#4			
	21B2	6002002E		varptr,#2			
	21B6	8940002E		varptr,#54			
	21BA	D7CA		window			
	21BC	F0		RET			
	21BE						
	242			HANNING:			
	243			0, 79, 315, 705, 1247, 1935, 2761, 3719			
	244	0004F003B01C102		4799, 5990, 7281, 8660, 10114, 11628, 13187, 14778			
	245	BF12661711CD421		16384, 17989, 19580, 21139, 22653, 24107, 25486, 26777			
	246	004045467C4C9352		27968, 29048, 30006, 30832, 31520, 32062, 32452, 32688			
	247	405D787136757078		32767, 32688, 32452, 32062, 31520, 30832, 30006, 29048			
	248	FF7F07FC47E3E7D		27968, 26777, 25486, 24107, 22653, 21139, 19580, 17989			
	249	405D99686E632B5E		16384, 14778, 13187, 11628, 10114, 8660, 7281, 5990			
	250	0040A3983336C2D		4799, 3719, 2761, 1935, 1247, 705, 315, 79			
	251	BF12870EC9A8F07		0			
	252	0000		0			
	253						
	254			\$reject			

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Listing 3—Main Routine (Continued)

ERR	LOC	OBJECT	SOURCE STATEMENT	ADDITIONAL TABLES FOR TESTING
255			CSRG AT 3D00H ; SINE 7.0 X	
256	3D00			
257				
258	3D00			
259	3D00	00003351B97D2E70	0, 20787, 32137, 28898, 12539, -9512, -27245, -32609	
260	3D10	7EA574F31C477C7A	-23170, -3212, 18204, 31356, 30273, 15446, -6393, -25329	
261	3D20	01800F9D08E7663C	-32767, -25329, -6392, 15446, 30273, 31356, 18204, -3212	
262	3D30	7EA59F809396D8DA	-23170, 32609, -27245, -9512, 12539, 28898, 32137, 20787	
263	3D40	0000CDAE77821E8F	-0, -20787, -32137, -28898, -12539, 9512, 27245, 32609	
264	3D50	825AB0C84B88485	23170, 3212, -18204, -31356, -30273, -15446, 6393, 25329	
265	3D60	FFFFF162F818AAC3	32767, 25329, 6392, -15446, -30273, -31356, -18204, 3212	
266	3D70	825A617F6D6A2B25	23170, 32609, 27245, 9512, -12539, -28898, -32137, -20787	
267				
268	3D80			
269	3D80	0000F555617FCF66	0, 22005, 32609, 26319, 6393, -16845, -31356, -29621	
270	3D90	05CF1F2B8270297C	-12539, 11039, 28898, 31785, 18204, -4808, -25329, -32728	
271	3DA0	7EA58BF933519C7E	-23170, -1608, 20787, 32412, 27245, 7962, -15446, -30852	
272	3DB0	BF9846C92825C96D	-30273, -14010, 9512, 28105, 32137, 19519, -3212, -24279	
273	3DC0	018029A174F33F4C	-32767, -24279, -3212, 19519, 32137, 28105, 9512, -14010	
274	3DD0	8F897C87AAC31A1F	-30273, -30852, -15446, 7962, 27245, 32412, 20787, -1608	
275	3DE0	7EA528800F9D38ED	-23170, -32728, -25329, -4808, 18205, 31785, 28898, 11039	
276	3DF0	05CF4B8C848533BE	-12539, -29621, -31356, -16845, 6393, 26319, 32609, 22005	
277				
278				
279	3E00			
280	3E00	0000C63C0F5A4AF8	0, 15558, 23055, 18607, 4520, -11910, -22169, -20942	
281	3E10	5FD07C1ECF4FC857	-8865, 7804, 20431, 22472, 12870, -3399, -17908, -23138	
282	3E20	03C08F7B693B8459	-16381, -1137, 14697, 22916, 19262, 5629, -10921, -21812	
283	3E30	55AC4FD9451A9E4D	-21403, -9905, 6725, 19870, 22721, 13800, -2271, -17165	
284	3E40	82A5738C21F7E835	-23166, -17165, -2271, 13800, 22721, 19870, 6725, -9905	
285	3E50	55ACCCAA58D5FD15	-21403, -21812, -10920, 5629, 19262, 22916, 14696, -1137	
286	3E60	03C09EA50CBA9F2	-16381, -23138, -17908, -3399, 12871, 22472, 20431, 7804	
287	3E70	5FD032AE67A97AD1	-8865, -20942, -22169, -11910, 4520, 18607, 23055, 15557	
288				
289	3E80			
290	3E80	0000FD04B40472FF	0, 1277, 1204, -142, -1338, -1119, 282, 1386	
291	3E90	00045CFE74FA693C	1024, -420, -1420, -919, 554, 1441, 804, -683	
292	3E90	58FA55FD2403A1F5	-1448, -683, 804, 1441, -1338, -142, 1204, 1277	
293	3E90	00946A051A01A108	1024, 1386, 282, -1119, -1338, -142, 1204, 1277	
294	3E90	000003FB4CFB8E00	-0, -1277, -1204, 142, 1338, 1119, -282, -1386	
295	3E90	000003FB4CFB8E00	-1024, 420, 1420, 919, -554, -1441, -804, 683	
296	3E90	00FC4A019C059703	1448, 683, -804, -1441, -554, 919, 1420, 420	
297	3E90	00FC4A019C059703	-1024, -1386, -282, 1119, 1338, 142, -1204, -1277	
298	3E90	A805A802DCC5FFA		
299	3E90	00FC96FA6FE5F04		
300				
301	3F00			

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```

ERR LOC OBJECT      LINE      SOURCE STATEMENT
3F00 0000C241C35E2148      302      DCW      0, 16834, 24259, 18465, 3182, -13029, -21886, -19557
3F10 5EE1D81C434A3164      303      DCW      -7842, 7394, 19011, 21553, 13425, -1368, -17103, -23821
3F20 5BBAE3F6BD3C245F      304      DCW      -17829, -1819, 15601, 24386, 19816, 4710, -12341, -22232
3F30 63D059DE5F1B3F49      305      DCW      -20379, -8519, 7007, 18761, 21383, 13658, -1067, -15888
3F40 82A5F6B76D727636      306      DCW      -23165, -18442, -3475, 13942, 24059, 20590, 6442, -11290
3F50 65A870AC64DA9419      307      DCW      -22427, -21382, -8600, 6548, 18708, 21475, 13892, -464
3F60 ABC48A68B618D0      308      DCW      -14933, -22466, -18712, -4840, 12317, 23391, 21861, 8225
3F70 5FD5C6A8ADABD9D5      309      DCW      -9889, -22328, -22451, -10791, 5857, 18749, 21861, 14281
311     
312     
3F80      313      END
ASSEMBLY COMPLETED, NO ERROR(S) FOUND.

```

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SERIES-III MCS-96 RELOCATOR AND LINKER, V2.0
Copyright 1983 Intel Corporation

INPUT FILES: :F2:FTMAIN.OBJ, :F2:FFTRUN.OBJ, :F2:PLOTSP.OBJ, :F2:A2DCON.OBJ

OUTPUT FILE: :F2:FFTOUT

CONTROLS SPECIFIED IN INVOCATION COMMAND:

IX

INPUT MODULES INCLUDED:

:F2:FTMAIN.OBJ(FFT_MAIN_APNOTE) 02/18/86

:F2:FFTRUN.OBJ(FFT_RUN) 02/18/86

:F2:PLOTSP.OBJ(PLOT_SERIAL) 02/18/86

:F2:A2DCON.OBJ(A2D_BUFFERING_UTILITY) 02/18/86

SEGMENT MAP FOR :F2:FFTOUT(FFT_MAIN_APNOTE):

	TYPE	BASE	LENGTH	ALIGNMENT	MODULE NAME
**RESERVED*		0000H	001AH		
	REG	001AH	0001H	BYTE	PLOT_SERIAL
*** GAP ***		001BH	0001H		
	REG	001CH	0008H	ABSOLUTE	FFT_MAIN_APNOTE
	OVRLY	0024H	0035H	ABSOLUTE	FFT_RUN
OVERLAP	OVRLY	0024H	0010H	ABSOLUTE	PLOT_SERIAL
OVERLAP	OVRLY	0024H	000CH	ABSOLUTE	FFT_MAIN_APNOTE
*** GAP ***		0059H	0001H		
	OVRLY	005AH	0006H	WORD	A2D_BUFFERING_UTILITY
	REG	0060H	000CH	WORD	A2D_BUFFERING_UTILITY
	REG	006CH	0003H	BYTE	FFT_MAIN_APNOTE
*** GAP ***		006FH	0011H		
	DATA	0080H	0080H	ABSOLUTE	FFT_MAIN_APNOTE
	STACK	0100H	001EH	WORD	
	DATA	011EH	0080H	WORD	FFT_RUN
*** GAP ***		019EH	0062H		
	DATA	0200H	0140H	ABSOLUTE	FFT_MAIN_APNOTE
*** GAP ***		0340H	1CC2H		
	CODE	2002H	0002H	ABSOLUTE	A2D_BUFFERING_UTILITY
*** GAP ***		2004H	007CH		
	CODE	2080H	01C0H	ABSOLUTE	FFT_MAIN_APNOTE
*** GAP ***		2240H	0040H		
	CODE	2280H	0215H	ABSOLUTE	FFT_RUN
*** GAP ***		2495H	006BH		
	CODE	2500H	0168H	ABSOLUTE	PLOT_SERIAL
	CODE	2668H	00ECH	BYTE	A2D_BUFFERING_UTILITY
*** GAP ***		2754H	10ACH		
	CODE	3800H	042AH	ABSOLUTE	FFT_RUN
*** GAP ***		3C2AH	00D6H		
	CODE	3D00H	0280H	ABSOLUTE	FFT_MAIN_APNOTE
*** GAP ***		3F80H	C080H		

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Listing 3—Main Routine (Continued)

Several constants are then setup for other routines. The purpose of centrally locating these constants was the ease of modifying the operation of the routines. Note that `AVR_NUM` and `SCALE_FACTOR` must be changed at the same time. `SCALE_FACTOR` is the shift count used to divide each FFT output value before it is added to the output array. `AVR_NUM` must be less than $2^{**}SCALE_FACTOR$ or an overflow could occur. Next, the public variables are declared for the arrays and a few other parameters.

The program then begins by setting the stack pointer and waiting for the SBE-96 to finish talking to the terminal. If this is not done, there may be serial port interrupts occurring for the first twenty five milliseconds of program operation.

Initialization of the plotter is next, followed by setting the `FFT_MODE` byte. This byte controls the graphing, loading and magnitude calculation of the FFT data. Since `FFT_MODE` is declared `PUBLIC` in this module, and `EXTERNAL` in the `PLOT` module and `FFTRUN` module, the extra bits available in this byte can be used for future enhancements.

The next step is to clear the FFT output array. Since the FFT program can be set to average its results by dividing the output before adding it to the magnitude array, the array must be cleared before beginning the program.

Data is then loaded into the FFT input array by the code at `LOAD_DATA`, or the code at `TABLE_LOAD`, depending on the value of `FFT_MODE` bit 0. The tabled data located at `DATA0` is a square wave of magnitude 1. This waveform provides a reasonable test of the FFT algorithm, as many harmonics are generated. The results are also easy to check as the pattern contains half zeros, imaginary values which are always the same, and real values which decrease. Figure 13 shows the output in fractions, hexadecimal and decimal. The hexadecimal and decimal values are based on an output of 16384 being equal to 1.00.

Note that the magnitude is

$$SQR (REAL^2 + IMAG^2)$$

and the dB value is

$$10 \text{ LOG } ((REAL^2 + IMAG^2)/65536)$$

The divide by 65536 is used for the dB scale to provide a reasonable range for calculations. If this was not done, a 32-bit LOG function would have been needed.

After the data is loaded, the data is optionally windowed, based on `FFT_MODE` bit 1, and the FFT program is called. Once the loop has been performed `AVR_CNT` times, the graph is drawn by the plot routine.

Appended to the main routine is the `FFTOUT.M96` Listing. This is provided by the relocater and linker, `RL96`. With this listing and the main program, it is possible to determine which sections of code are at which addresses.

Using the modular programming methods employed here, it is reasonably easy to debug code. By emulating the program in a relatively high level language, each routine can be checked for functionality against a known standard. The closer the high level implementation matches the `ASM96` version, the more possible checkpoints there are between the two routines.

Once all of the program routines (modules) can be shown to work individually, the main program should work unless there is unwanted interaction between the modules. These interactions can be checked by verifying the inputs and outputs of each module. The assembly language locations to perform the program breaks can be retrieved by absolutely locating the main module. The other modules can be dynamically located by `RL96`.

The more interactive program modules are, the more difficult the program becomes to debug. This is especially true when multiple interrupts are occurring, and several of the interrupt routines are themselves interruptable. In these cases, it may be necessary to use debugging equipment with trace capability, like the `VLSiCE-96`. If this type of equipment is not available, then using I/O ports to indicate the entering and leaving of each routine may be useful. In this way it will be possible to watch the action of the program on an oscilloscope or logic analyzer. There are several places within this code that I/O port toggling has been used as an aid to debugging the program. These lines of code are marked "FOR INDICATION ONLY."

K	Fractional			dB	Decimal			Hexadecimal		
	REAL	IMAG	MAG ²		REAL	IMAG	MAG ²	REAL	IMAG	MAG ²
0	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
1	0.0625	-1.2722	1.2738	38.225	1024	-20843	20868	400	AE95	5184
2	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
3	0.0625	-0.4213	0.4260	28.710	1024	-6903	6978	400	E509	1B42
4	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
5	0.0625	-0.2495	0.2572	24.329	1024	-4088	4214	400	F008	1076
6	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
7	0.0625	-0.1747	0.1855	21.491	1024	-2862	3039	400	F4D2	BDF
8	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
9	0.0625	-0.1321	0.1462	19.421	1024	-2165	2395	400	F78B	95B
10	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
11	0.0625	-0.1043	0.1216	17.820	1024	-1708	1992	400	F954	7C8
12	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
13	0.0625	-0.0843	0.1049	16.540	1024	-1381	1719	400	FA9B	6B7
14	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
15	0.0625	-0.0690	0.0931	15.499	1024	-1130	1525	400	FB96	5F5
16	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
17	0.0625	-0.0566	0.0844	14.645	1024	-928	1382	400	FC60	566
18	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
19	0.0625	-0.0464	0.0778	13.944	1024	-759	1275	400	FD09	4FB
20	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
21	0.0625	-0.0375	0.0729	13.374	1024	-614	1194	400	FD9A	4AA
22	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
23	0.0625	-0.0296	0.0691	12.918	1024	-484	1133	400	FE1C	46D
24	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
25	0.0625	-0.0224	0.0664	12.564	1024	-366	1088	400	FE92	440
26	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
27	0.0625	-0.0157	0.0644	12.305	1024	-256	1056	400	FF00	420
28	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
29	0.0625	-0.0093	0.0632	12.135	1024	-152	1035	400	FF68	40B
30	0.0000	0.0000	0.0000	0.000	0	0	0	0	0	0
31	0.0625	-0.0031	0.0626	12.051	1024	-50	1025	400	FFCE	401

Figure 13. FFT Output for a Square Wave Input

9.0 ANALOG TO DIGITAL CONVERTER MODULE

The module presented in Listing 4 is a general purpose one which converts analog values under interrupt control and stores them in one of two buffers. These buffers

can then be downloaded to another buffer, such as the input buffer to the FFT program. During downloading, this module can convert the data into signed or unsigned formats, and fill a linear or a paired array. A paired array is like the one used in the FFT transform program. It requires N data points placed alternately in two arrays, one starting at zero and the other at N/2.

```

MCS-96 MACRO ASSEMBLER      A2D_BUFFERING_UTILITY
SERIES-III MCS-96 MACRO ASSEMBLER, V1.0
SOURCE FILE: F2:A2DCON.A96
OBJECT FILE: F2:A2DCON.OBJ
CONTROL$ SPECIFIED IN INVOCATION COMMAND: NOSB

```

```

ERR LOC OBJECT      LINE  SOURCE STATEMENT
1  $pageLength(50)
2
3  A2D_Buffering_Utility  module  stacksize(12)
4
5  ; Intel Corporation, July 16, 1985
6  ; by Dave Ryan, Intel Applications Engineer
7
8  ; This utility fills a memory buffer with A/D conversion results. The
9  ; conversions are done under interrupt control, and are initiated when
10 ; A2D_BUFF_Util is called. The results of the conversions are placed
11 ; in one of two buffers, called BUFF0 and BUFF1.
12
13 ; This utility provides options for the selection of the buffer lengths, data
14 ; format, sample period, conversion channel and time base. The utility also
15 ; has a download routine that will load either buffer into a register file
16 ; buffer. Output formats can also be chosen for the downloaded buffer. The
17 ; data can be formatted as signed or unsigned linear or paried arrays.
18
19 ; RUN-TIME OPTIONS
20
21 ; Rather than use the STACK to pass controls, this utility gets its directions
22 ; from 2 control words in memory. The utility expects that its control words
23 ; are valid at the time A2D_BUFF_Util is called and remain valid throughout
24 ; A/D interrupt executions and downloads. The control words are:
25
26     Sample_Period    ; WORD ; The time between samples in timer counts
27                     ;       ; where the timer used has been specified
28
29
30     Control_A2D      ; BYTE ; Control information for the utility:
31                     ; BIT#
32
33                     ; 0-2 ; Channel Number
34                     ; 3 ; Signed Result/Unsigned Result#
35                     ; 4 ; Convert/Download#
36                     ; 5 ; BUFF1/BUFF0# for conversions
37                     ; BUFF0/BUFF1# for downloads
38                     ; 6 ; Linear/Paired#
39                     ; 7 ; Converter BUSY/IDLE#
40
41 $EJECT

```

Listing 4—A to D Converter Routine

MCS-96 MACRO ASSEMBLER A2D_BUFFERING_UTILITY 02/18/86 PAGE 2

ERR LOC OBJECT LINE SOURCE STATEMENT

```

42      ;
43      ; The following is a table of equates that can be used to simplify the
44      ; bit diddling requirements. If you are not running conversions concurrently
45      ; with downloads, always LDB Control_A2D with the following command then
46      ; ORB Control_A2D with the channel number you wish to convert if you are
47      ; starting a conversion.
48      ;
49      ; Once the utility is called, care must be taken when Control_A2D is
50      ; modified. You can cause downloads to occur while conversions are running,
51      ; but you cannot start conversions during a download. To do this, ORB to the
52      ; control byte with the appropriate bits set. Do NOT change the BUFF bit or
53      ; the BUSY bit. Just set the download bit and set the data format bits to the
54      ; correct values.
55      ;
56      ; The BUFF bit has opposite definitions for conversions and downloads. This
57      ; allows conversions to be done into BUFF0 while downloads come from BUFF1, and
58      ; vice versa.
59      ;
60      ; A2D UTILITY COMMANDS
61      ;
62      ; con_b0 equ 00010000b; convert to BUFF0
63      ; con_b1 equ 00110000b; " BUFF1
64      ;
65      ; dump_b0_l_u equ 01100000b; download BUFF0 as LINEAR UNSIGNED data
66      ; dump_b1_l_u equ 01000000b; " BUFF1 " " "
67      ; dump_b0_p_u equ 00100000b; " " PAIRED " "
68      ; dump_b1_p_u equ 00000000b; " " " "
69      ; dump_b0_l_s equ 01101000b; download BUFF0 as LINEAR SIGNED data
70      ; dump_b1_l_s equ 01001000b; " " " "
71      ; dump_b0_p_s equ 00101000b; " " PAIRED " "
72      ; dump_b1_p_s equ 00001000b; " " " "
73      ;
74      $ject

```

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Listing 4—A to D Converter Routine (Continued)

MCS-96 MACRO ASSEMBLER	A2D_BUFFERING_UTILITY	02/18/86	PAGE 3
ERR LOC OBJECT	SOURCE STATEMENT		

```

75 ;
76 ; ASSEMBLY-TIME OPTIONS
77 ;
78 ; The base addresses and length of each conversion buffer and the destination
79 ; buffer are DECLARED EXTERNAL in this utility. Other options such as selection
80 ; of the timer used as a timebase, the length of the buffer, and the effective
81 ; number of bits in the reported result are set at assembly time through use
82 ; of EQUates in this module.
83 ;
84 ; The following parameters need to be provided at assembly or link time.
85 ; The buffer bases are declared EXTERNAL by this utility, while the buffer
86 ; length shift count and HSO commands are EQUated.
87 ;
88 ; BUFF0_BASE ; The starting address of BUFF0
89 ; BUFF1_BASE ; The starting address of BUFF1
90 ; DEST_BUFF_BASE ; The starting address of the download
91 ; ; target buffer.
92 ;
93 ; BUFF_LENGTH ; The number of SAMPLES that each
94 ; ; buffer must hold. must be >1 and <256
95 ;
96 ; Shift_count ; The number of times that the conversion result is
97 ; ; to be shifted right from its natural left justified
98 ; ; position. Setting a shift count greater than 6 will
99 ; ; result in lost bits to the right. Rounding is NOT
100 ; ; done.
101 ;
102 ; CLOCK ; Specify as either TIMER1 or T2CLK. This is the
103 ; ; timebase used for conversions.
104 ;
105 ; Samples are stored as words in the buffers. The program stores
106 ; conversions linearly in BUFF0 and BUFF1, and linearly or paired in the
107 ; destination buffer as selected. If the download is to be paired, the first
108 ; sample is placed in location DEST_BUFF_BASE, the second sample is placed in
109 ; location (DEST_BUFF_BASE + BUFF_LENGTH), the third in (DEST_BUFF_BASE + 2),
110 ; the fourth in (DEST_BUFF_BASE + 2 + BUFF_LENGTH), etc.
111 ;
112 $eject

```

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Listing 4—A to D Converter Routine (Continued)

MCS-96 MACRO ASSEMBLER	A2D_BUFFERING_UTILITY	02/18/86	PAGE	4
ERR LOC OBJECT				

LINE	SOURCE STATEMENT
113	;
114	;
115	;
116	;
117	;
118	;
119	;
120	;
121	;
122	;
123	;
124	;
125	;
126	;
127	;
128	;
129	;

; NOTES ON EXECUTION
 ; When a utility call directs the initiation of a set of A2D conversions, the
 ; first conversion is begun at approximately one sample time plus 50 state
 ; times from when the utility was called. This assumes that no interrupts are
 ; present.
 ; The conversion busy bit is set approximately 50 state times after a call
 ; to the utility, if the convert bit was set in the A2D Control byte. The
 ; busy bit is cleared after all conversion results have been stored in the
 ; result buffer designated (BUFF0 or BUFF1).
 ; Take great care in modifying the A2D Control byte to do a download while
 ; conversions are taking place. You can never download a buffer that is
 ; being converted into. The results would be invalid.
 ; reject

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Listing 4—A to D Converter Routine (Continued)

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```

MCS-96 MACRO ASSEMBLER      A2D_BUFFERING_UTILITY
ERR LOC OBJECT
0000
130
131      RSRG
132
133      EXTRN BUFF0_BASE, BUFF1_BASE, DEST_BUFF_BASE
134      EXTRN ad_command, ad_result_lo, ad_result_hi
135      EXTRN hso_command, hso_time, sp
136
137      BUFF_LENGTH      EQU 64
138      Shift_Count      EQU 1
139      CLOCK             EQU TIMER1
140
141      ; set up hso commands for correct timer *****
142      TIMER1            equ 0AH
143      T2CLK              equ 0CH
144
145      MASK              equ (10h*CLOCK)AND(40h)
146
147      Start_A2D         equ (00001111b)OR(MASK)
148      ;start a2d based on timer 1, no interrupt
149
150
151      HSO_0_Low          equ (00000000b)OR(MASK)
152      ; make hso.0 low based on timer1 no interrupt
153
154      HSO_0_High         equ (00100000b)OR(MASK)
155      ; make hso.0 hi based on timer1 no interrupt
156
157
158      ; set up storage *****
159
160      adudtemp0:         DSW 1; temp register for download calls
161
162      aductemp0:         DSW 1; temp registers for conversion calls
163      aductemp1:         DSW 1
164      top_of_buffer:     DSW 1
165      sample_count:     DSB 1
166
167      Control_A2D:       DSB 1; the byte that controls the utility execution
168                          DForm 3 ; Signed/Unsigned#
169                          Con_Dwn equ 4 ; Convert/Download#
170                          B0_B1 equ 5 ; Buff1/Buff0# for conversions
171                          ; Buff0/Buff1# for downloads
172                          Lin_Far equ 6 ; Linear/Paired#
173                          Busy equ 10000000B ; Bit 8
174      $eject

```

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Listing 4—A to D Converter Routine (Continued)

MCS-96 MACRO ASSEMBLER	A2D_BUFFERING UTILITY	02/18/86	PAGE 6
ERR LOC OBJECT	LINE SOURCE STATEMENT		
000A	175 Sample_Period: DSW 1; the word that specifies the number of clock ticks		
	176 ; that elapse between each sample		
	177 PUBLIC Control_A2D, Sample_Period		
	178		
	179		
	180		
	181		
0000	182 OSEG		
	183		
0000	184 src_ptr: DSW 1; some overlayable temp registers		
0000	185 temp set src_ptr:WORD		
0002	186 dest_ptr: DSW 1		
0004	187 loop_count: DSW 1		
	188		
	189		
2002	190 CSRG at 2002h		
	191		
	192 PUBLIC A2D_DONE_Vector		
	193		
2002 AC00	194 DCW A2D_DONE_Vector		
	195		
	196		
0000	197 CSRG		
	198		
	199 PUBLIC A2D_BUFF_Util		
	200		
	201 Load_HSO_Command MACRO var ; Macro to load HSO		
	202		
	203 LDH hao_command,\$var		
	204 LD hao_time,aductemp0		
	205 ENDM		
	206 \$rejet		

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Listing 4—A to D Converter Routine (Continued)

MCS-86 MACRO ASSEMBLER			A2D_BUFFERING_UTILITY		02/18/86	PAGE 7
ERR	LOC	OBJECT	LINE	SOURCE STATEMENT		
0000			207			
			208	A2D_BUFF_Util:		
0000	3C0962		209			
0003		R	210	JBS Control_A2D, Con_Dwn, Convert ; Select convert or download		
0003	A1000000	E	211	Download:		
0007	350904	R	212	LD src_ptr, #BUFF1_BASE		
		R	213	JBC Control_A2D, B0_B1, Set_Data_Format		
000A			214			
		E	215	Download_BUFF0:		
000A	A1000000		216	LD src_ptr, #BUFF0_BASE		
			217			
000E			218			
000E	A1000002	E	219	Set_Data_Format:		
0012	B14004	R	220	LD dest_ptr, #DEST_BUFF_BASE ; Choose linear or paired		
0015	3E091D	R	221	LD loop_count, #BUFF_LENGTH		
		R	222	JBS Control_A2D, Lin_Par, Linear_data_loop		
			223			
0018	180104	R	224	PAIRED: SHRB loop_count, #1 ; The paired data routine uses 1/2		
			225			
001B		R	226	Paired_Data_loop:		
001B	A20000	R	227	LD adutemp0, [src_ptr]+ ; Move even word		
001E	C20200	R	228	ST adutemp0, [dest_ptr]		
0021	65400002	R	229	ADD dest_ptr, #BUFF_LENGTH ; Length = # of words = 1/2 # of bytes		
		R	230			
0025	A20000	R	231	LD adutemp0, [src_ptr]+ ; Move odd word		
0028	C20200	R	232	ST adutemp0, [dest_ptr]+		
002B	69400002	R	233	SUB dest_ptr, #BUFF_LENGTH		
		R	234			
002F	E004E9	R	235	DJNZ loop_count, Paired_Data_loop ; Loop until done		
			236			
0032	280D		237	CALL Convert_Data		
0034	F0		238	RET		
			239			
			240			
0035			241	Linear_Data_loop:		
0035	A20000	R	242	LD adutemp0, [src_ptr]+ ; Move data linearly		
0038	C20200	R	243	ST adutemp0, [dest_ptr]+		
		R	244			
003B	E004F7	R	245	DJNZ loop_count, Linear_Data_loop ; Loop until done		
			246			
003E	2801		247	CALL Convert_Data		
0040	F0		248	RET		
			249			
			250	\$sect		

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Listing 4—A to D Converter Routine (Continued)

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MCS-86 MACRO ASSEMBLER

A2D_BUFFERING_UTILITY

ERR LOC OBJECT

LINE

SOURCE STATEMENT

251 Convert_Data: ; Convert the data in the destination buffer

252 LD

loop_count,#BUFF_LENGTH

src_ptr,#DEST_BUFF_BASE

253 LD

loop_count,#BUFF_LENGTH

src_ptr,#DEST_BUFF_BASE

254 LD

loop_count,#BUFF_LENGTH

src_ptr,#DEST_BUFF_BASE

255 LD

loop_count,#BUFF_LENGTH

src_ptr,#DEST_BUFF_BASE

256 Again: LD

adudtemp0,[src_ptr]

adudtemp0,#11000000b

257 ANOB

adudtemp0,[src_ptr]

adudtemp0,#11000000b

258 JBC

adudtemp0,[src_ptr]

adudtemp0,#11000000b

259 JBC

adudtemp0,[src_ptr]

adudtemp0,#11000000b

260 Control_A2D, DForm, Unsigned_Result

adudtemp0,[src_ptr]

adudtemp0,#11000000b

261 Signed_Result:

adudtemp0,[src_ptr]

adudtemp0,#11000000b

262 SUB

adudtemp0,[src_ptr]

adudtemp0,#11000000b

263 SHRA

adudtemp0,[src_ptr]

adudtemp0,#11000000b

264 BR

adudtemp0,[src_ptr]

adudtemp0,#11000000b

265 Replace_Sample

adudtemp0,[src_ptr]

adudtemp0,#11000000b

266 Unsigned_Result:

adudtemp0,[src_ptr]

adudtemp0,#11000000b

267 SHR

adudtemp0,[src_ptr]

adudtemp0,#11000000b

268 adudtemp0,#Shift_Count

adudtemp0,[src_ptr]

adudtemp0,#11000000b

269 Replace_Sample:

adudtemp0,[src_ptr]

adudtemp0,#11000000b

270 ST

adudtemp0,[src_ptr]

adudtemp0,#11000000b

271 DJNZ

adudtemp0,[src_ptr]

adudtemp0,#11000000b

272 Loop_count,Again ; Loop until done

adudtemp0,[src_ptr]

adudtemp0,#11000000b

273 RET

adudtemp0,[src_ptr]

adudtemp0,#11000000b

274

adudtemp0,[src_ptr]

adudtemp0,#11000000b

275 Convert:

adudtemp0,[src_ptr]

adudtemp0,#11000000b

276 ;: Prepare to Start Conversions

adudtemp0,[src_ptr]

adudtemp0,#11000000b

277 PUSHF

adudtemp0,[src_ptr]

adudtemp0,#11000000b

278 ORB

adudtemp0,[src_ptr]

adudtemp0,#11000000b

279 Control_A2D, #Busy

adudtemp0,[src_ptr]

adudtemp0,#11000000b

280 sample_count,#BUFF_LENGTH - 1

adudtemp0,[src_ptr]

adudtemp0,#11000000b

281 LDB

adudtemp0,[src_ptr]

adudtemp0,#11000000b

282 top_of_buffer,#BUFF0_BASE

adudtemp0,[src_ptr]

adudtemp0,#11000000b

283 LD

adudtemp0,[src_ptr]

adudtemp0,#11000000b

284 LD

adudtemp0,[src_ptr]

adudtemp0,#11000000b

285 LD

adudtemp0,[src_ptr]

adudtemp0,#11000000b

286 JBC

adudtemp0,[src_ptr]

adudtemp0,#11000000b

287 Control_A2D, B0_B1, Start_Conversions

adudtemp0,[src_ptr]

adudtemp0,#11000000b

288 top_of_buffer,#BUFF1_BASE

adudtemp0,[src_ptr]

adudtemp0,#11000000b

289 LD

adudtemp0,[src_ptr]

adudtemp0,#11000000b

290 \$reject

adudtemp0,[src_ptr]

adudtemp0,#11000000b

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Listing 4—A to D Converter Routine (Continued)

MCS-96 MACRO ASSEMBLER	A2D_BUFFERING_UTILITY	02/18/86	PAGE 9
ERR LOC OBJECT	LINE SOURCE STATEMENT		
007F	290 Start_Conversions:		
	291		
007F 51070900	292 ANDB ad_command,Control_A2D,#00000111b ;load channel number		
0083 440A0A02	293		
	294 ADD aductemp0,CLOCK.Sample_Period ;start first conversion		
	295		
	296		
	297 ;one sample time from		
	298 ;now		
	299		
	300		
008D CC00	301 Load_HSO_Command Start_A2D ; Start A2D at Time=aductemp0		
	302		
	303 POP temp ; get a copy of the psw		
	304		
	305 Load_HSO_Command HSO_0_high ; set hso.0 high at conversion		
	306		
	307 ; start time for external S/H		
0095 81020200	308 OR temp,#202h ; enable a2d interrupts		
	309		
0099 640A02	310 ADD aductemp0,Sample_Period ; start second conversion one		
	311		
	312		
	313		
	314		
	315		
	316 Load_HSO_Command Start_A2D ; sample time from the first		
	317		
	318		
00A2 C800	319 PUSH temp ; put psw back on stack		
	320		
	321		
	322		
	323		
	324		
	325		
	326 Load_HSO_Command HSO_0_low ;lower hso.0 for external S/H		
	327		
00AA F3	328 POPF		
00AB F0	329 RET		
	330		
	331 \$reject		

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Listing 4—A to D Converter Routine (Continued)

MCS-96 MACRO ASSEMBLER A2D_BUFFERING_UTILITY 02/18/86 PAGE 10

```

ERR LOC OBJECT      LINE      SOURCE STATEMENT
00AC                    332      CSRG
00AC                    333     
00AC F2                334      A2D_DONE_Vector:      ; A/D INTERRUPT ROUTINE
00AC                    335      PUSHF
00AD C60600            336     
00AD C60600            337      STB      ad_result_lo,[top_of_buffer]+
00AD C60600            338      STB      ad_result_hi,[top_of_buffer]+
00B3 51070500          339      ANDB      ad_command,Control_A2D,#00000111b      ; load channel number
00B7 E00809            340     
00B8 1708              341      DJNZ      sample_count, Sample_Again
00B8                    342      INCB      sample_count
00B8                    343     
00B8 880406            344      CMP      top_of_buffer,aductempl      ; Check top of buffer
00B8 DF26              345      BE      Top_of_buffers
00C1 F3                346      POPF
00C2 F0                347      RET
00C3                    348     
00C3                    349      Sample_Again:
00C3 640A02            350      ADD      aductemp0,Sample_Period
00C5 880406            351      CMP      top_of_buffer,aductempl      ; Set next sample time
00C5                    352     
00C5                    353      Load_HSO_Command Start_A2D      ; Check top of buffer
00C5                    354     
00CF 30080B            357      JBC      sample_count,0,Make_HSO_High      ; for later jump
00D2                    358     
00D2                    359      Make_HSO_low:
00D2 F0                360      nop      ; wait 8 states after HSO load
00D2                    361     
00D2                    362      Load_HSO_Command HSO_0_Low      ; Load for change of HSO to trigger S/H
00D2                    363     
00D9 DF0C              366      BE      Top_of_buffers
00D9 F3                367     
00D9 F3                368      POPF
00DC F0                369      RET
00DD                    370     
00DD                    371      Make_HSO_high:
00DD                    372      Load_HSO_Command HSO_0_High      ; Load for change of HSO to trigger S/H
00DD                    373     
00E3 DF02              376      BE      Top_of_buffers
00E3 F3                377     
00E3 F3                378      POPF
00E6 F0                379      RET
00E7                    380     
00E7                    381      Top_of_buffers:
00E7 717F09            381      ANDB      Control_A2D,#NOT(busy)      ; Clear converter BUSY bit
00E8 F3                382     
00E8 F3                383      POPF
00EE F0                384      RET
00EC                    385      END
ASSEMBLY COMPLETED, NO ERROR(S) FOUND.

```

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Listing 4—A to D Converter Routine (Continued)

The listing contains a fairly complete description of what the program does. The block by block operations are shown below:

Lines 1-198 describe the program, declare the variables and set up equates. Several of these variables are declared as overlayable, so the user needs to be careful if using this module for other than the FFT program.

Lines 205-210 declare a macro which is used to load the HSO unit. This will be used repeatedly through the code.

Lines 212-253 determine whether a conversion or download has been requested. If a download has been requested, the data is downloaded to the destination array as either paired or linear data. Paired data has been described earlier.

Lines 255-278 contain a subroutine which converts the destination array to either signed or unsigned numbers. The numbers are also shifted right to provide the desired full-scale value as requested by `SHIFT__COUNT`.

Lines 279-334 initialize the conversion routine. `HSO.0` is toggled with the start of each routine so that an external sample and hold can be used. The instructions in lines 308, 316, and 326 have been interweaved with the `Load__HSO__Commands` to provide the required 8 state delays between HSO loadings. If this was not done, NOPs would have been needed. It is easier to understand the code if these lines are thought of as being gathered at line 326.

Lines 337-353 are the actual A/D interrupt routine. The A/D results are placed BYTE by BYTE on the buffer, the A/D is reloaded, and then the number of samples taken is compared to the number needed. Note that the A/D command register needs to be reloaded even if the channel does not change. `INCB` on line 348 is used to insure that the `DJNZ` falls through on the next pass (if `sample__count` is not reset).

Lines 355-396 complete the routine. The HSO is set up to trigger the next conversion and provide the `HSO.0` toggle for an external sample and hold. Once again, the time between consecutive loads of the HSO is 8 states minimum. Note that this section of code has been optimized for speed by reducing branches to an absolute minimum and duplicating code where needed.

This concludes the description of the A to D buffer module. In the FFT program, this module is run, then the FFT transform module, then the plot module. This allows variables to be overlaid, saving RAM space. The time cost for this is not bad, considering the printer is the limiting factor in these conversions. If more RAM

was provided, and the FFT was run with its data in external RAM, this module could be run simultaneously with the other modules.

10.0 DATA PLOTTING MODULE

The plot module is relatively straight-forward, and is shown in Listing 5. After the declarations, which include overlayable registers, an initialization routine is listed. This separately called routine sets up the serial port on the 8096 to talk to the printer. In this case, the port has to be set for 300 baud.

A console out routine follows. This routine can also be called by any program, but it is used only by the plot routine in this example. The write to port 1 is used to trace the program flow. The character to be output is passed to this routine on the stack. This conforms to PLM-96 requirements.

Since all stack operations on the 8096 are 16-bits wide, a multiple character feature has been added to the console out routine. If the high byte it receives is non-zero, the ASCII character in that byte is printed after the character in the low byte. If the high byte has a value between 128 and 255, the character in the low byte is repeated the number of times indicated by the least significant 7 bits of the high byte.

The print decimal number routine is next. It is called with two words on the stack. The first word is the unsigned value to be printed. The second byte contains information on the number of places to be printed and zero and blank suppression. This routine is not overflow-proof. The user must declare a sufficient number of places to be printed for all possible numbers.

The `DRAW__GRAPH` routine provides the plot. It first sends a series of carriage return, line feeds (CRLFs) to clear the printer and provides a margin on the paper. Each row is started with the row number, 2 spaces, and a "+". Asterisks are then plotted until

Number of asterisks > FFT Value / `PLOT__RES`

Recall that `PLOT__RES` is a variable set by the main program. When the number of asterisks hits the desired value, the value of the line is printed. If the Decibel mode is selected, the line value is divided by 512 and printed in integer + decimal part form, followed by "dB". If the number of asterisks reaches `PLOT__MAX`, no value is printed. The next line is then started. A line with only a "!" is printed before the next plot line to provide a more aesthetic display on the printer. If a CRT was used, this extra line would probably not be wanted.

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MCS-96 MACRO ASSEMBLER PLOT_SERIAL
 SERIES-III MCS-96 MACRO ASSEMBLER, V1.0
 SOURCE FILE: :F2:PLOTSP.A96
 OBJECT FILE: :F2:PLOTSP.OBJ
 CONTROLS SPECIFIED IN INVOCATION COMMAND: NOSB

```

ERR LOC OBJECT LINE SOURCE STATEMENT
1 1 $pagelength(50)
2 2
3 3 PLOT_SERIAL MODULE STACKSIZE (6)
4 4
5 5 ; Intel Corporation, December 12, 1985
6 6 ; by Ira Horden, MCO Applications
7 7
8 8 ; This program produces a plot on serially connected printer. The
9 9 ; magnitude of each of the 32 input values is plotted horizontally, with one
10 10 ; "i" followed by a linefeed between each plot line. Each plot line starts
11 11 ; with a "i," and the entire plot begins with 3 line feeds and ends with a form
12 12 ; feed. The values to be plotted are 32 unsigned words based at the externally
13 13 ; defined pointer PLOT_IN.
14 14
15 15 ; The routine INIT_OUTPUT must be run to set up the serial port when the
16 16 ; system is turned on. CON_OUT can be used by a program to output to the
17 17 ; serial port. DRAW_GRAPH is the routine that automatically plots the data.
18 18
19 19 ; Sizing of the graph can be done using PLOT_RES, which determines how many
20 20 ; units are needed for each dot, and PLOT_MAX, which is the maximum value the
21 21 ; program will be passed. Note that (PLOT_MAX/PLOT_RES) defines the maximum
22 22 ; number of columns the routine will print.
23 23 ;
24 24 RSEG
25 25
26 26 EXTRN ioc1, baud_reg, spcon, spatat, sbuf, port1
27 27 EXTRN zero, ax, bx, cx, dx, fpt_mode
28 28 spump: dsb 1
29 29
30 30 OSEG at 24H
31 31 value: ds1 1
32 32 divisor: ds1 1
33 33 xptr: ds1 1
34 34 yptr: ds1 1
35 35 xval: ds1 1
36 36 log_val: ds1 1
37 37
38 38 DSEG
39 39 EXTRN PLOT_IN
40 40
41 41 $eject

```

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Listing 5—The Plot Module

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PLOT_SERIAL

MCS-86 MACRO ASSEMBLER

ERR LOC OBJECT

LINE

SOURCE STATEMENT

```

2500      42 CSEG at 2500H      ;;;;      PROGRAM MODULE BEGINS
      43
      44 PUBLIC INIT_OUTPUT, CON_OUT, DRAW_GRAPH
      45 EXTRN PLOT_RES, PLOT_RES_2, PLOT_MAX
      46
      47 INIT_OUTPUT:
      48      ; INITIALIZE SERIAL PORT
      49
      50      iocl,#00100000B ; set p2.0 to txd
      51
      52      baud_val      equ 624      ; 624=300 baud (at 12 MHz)
      53
      54      Baud_high      equ ((baud_val-1)/256) OR 80H      ; set for XTALL clock
      55      Baud_low       equ (baud_val-1) MOD 256
      56
      57      baud_reg,#baud_low
      58      baud_reg,#baud_high
      59
      60      ldb          ldb          ; enable receiver mode 1
      61      ldb          spcon,#01001001b      ; set TI-tmp
      62      ldb          sptmp,#00100000B
      63      RET
      64
      65      $reject

```

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Listing 5—The Plot Module (Continued)

Call with a word parameter on stack. The low byte has the character to be sent. If the high byte has a value between 81H and 8FEH, the character is repeated 1 to 126 times respectively. One repeat means that the character will be printed 2 times. If the high byte contains a value between 1 and 7FH, the character represented by that value will be printed after the character in the low byte. If the high byte contains a value of zero only the low byte will be printed.

```

2510 CON_OUT:
2511     pop     ax          ; cx contains the calling address
2512     pop     dx          ; If bit 7 is set print one character
2513     jbs     dx+1,7,onechr ; if highbyte=0 print one character
2514     cmb     dx+1,zero
2515     je      onechr
2516
2517     twochr:
2518     orb     sptmp,sptstat ; wait for TI
2519     jbc     sptmp,5,twochr ; clear TI--tmp
2520     andb    sptmp,#10111111b ; remove possible false TI
2521     orb     zero,sptstat
2522
2523     ldb     sbuf,dx
2524     dx,dx+1
2525     clrb    dx+1
2526     andb    dx,#07FH
2527
2528     onechr:
2529     incb    dx+1
2530     andb    dx+1,#7FH
2531     waitl:
2532     orb     sptmp,sptstat ; wait for TI
2533     jbc     sptmp,5,waitl ; clear TI--tmp
2534     andb    sptmp,#10111111b ; remove possible false TI
2535     orb     zero,sptstat
2536
2537     ldb     sbuf,dx
2538     dx+1,waitl
2539     BR      [ax]
2540
2541     $eject

```

Listing 5—The Plot Module (Continued)

```

107 :
108 :
109 :
110 :
111 :
112 :
113 :
114 :
115 :
116 :
117 :
118 :
119 :
120 :
121 :
122 :
123 :
124 :
125 :
126 :
127 :
128 :
129 :
130 :
131 :
132 :
133 :
134 :
135 :
136 :
137 :
138 :
139 :
140 :
141 :
142 :
143 :
144 :
145 :
146 :
147 :
148 :
149 :
150 :
151 :
152 :
153 :
254C :
254C C000
254E C000
2550 AC0100
2553 A300962528
2558 C024
255A 0126
255C 8C2824
255F 380017
2562 980024
2565 D70F
2567
2567 310003
256A 38280C
256D 3A0015
2570 A1F00024
2574 2003
2576 910100
2579 65300024
257D 617F0024
2581 C824
2583 2F8B
2585 A02524
2588 012A
258A 8B0A0028
258E 880028
2591 D7C7
2593
2593 E300
2596
2596 000001000A006400

PRINT_NUM:
    pop     cx          ; Send Decimal number to CON_OUT
    pop     bx          ; bx is mode byte, bx+1 is divisor pointer
    ld     dx,bx+1
    ld     divisor,divtab[dx]
    pop     value
    div_loop:
        value+2
        value,divisor
        bx,0,chr_ok
        value,zero
        non_0
        ; Value is zero
        bx,1,prntsp
        divisor,0,chr_ok
        bx,2,cont
        value,#0F0H
        chr_ok
        non_0:
            orb     bx,#0001B
            value,#30h
            and     value,#7Fh
            push    value
            call    con_out
            value,value+2
            ld     divisor+2
            clr     divisor,#10
            cmp     divisor,zero
            div_loop
            br     [cx]
        DIVTAB:
            dcw     0, 1, 10, 100, 1000, 10000
            ; divisor table - 10**n

; Call with two words on stack. The first is the value to be printed.
; The second has mode information in the low byte.
; MODE: 000 = suppress all zeros
; 001 = print all numbers
; 010 = suppress all zeros except rightmost
; 1xx = do not print leading blanks
; The high byte of the 2nd word = 2x the number of places to be printed

```

```

MCS-86 MACRO ASSEMBLER      PLOT_SERIAL
ERR LOC  OBJECT              LINE  SOURCE STATEMENT
154
155
156
157
158          DRAW_GRAPH:      push    #0dh
159                          call    con_out
160                          ;;      Clear 3 lines
161                          push    #820AH
162                          call    CON_OUT
163                          push    #00
164                          call    con_out
165
166                          clr     xptr
167                          clr     xval
168
169          NMT_ROW:          push    #0A00H
170                          call    CON_OUT
171                          push    #00H
172                          call    CON_OUT
173
174                          push    xval
175                          push    #(0A00H or 0010b)
176                          call    PRINT_NUM
177
178                          push    #2020H
179                          call    CON_OUT
180                          push    #2BH
181                          call    con_out
182
183                          ld      yptr, #PLOT_RES_2
184
185          NMT_COL:          cmp     yptr, PLOT_IN[xptr]
186                          jb      PRT_NUM
187
188          PRT_MK:          push    #2AH
189                          call    CON_OUT
190
191          INC_CNT:          add     yptr, #PLOT_RES
192                          cmp     yptr, #PLOT_MAX
193                          jnh     NMTLN
194
195                          br      $eject
196
197
25A2
25A3 C90000
25A4 2F69
25A5 C90A82
25A6 2F64
25A7 C90000
25A8 2F5F
25A9 012C
25AA 0130
25AB C90D0A
25AC 2F56
25AD C90000
25AE 2F51
25AF C830
25B0 C9020A
25B1 2F86
25B2 C92020
25B3 2F45
25B4 C92800
25B5 2F40
25B6 A100002E
25B7
25B8 882D00002E
25B9 D911
25BA
25BB C92A00
25BC 2F30
25BD
25BE 6500002E
25BF 8900002E
25C0 D1EA
25C1 204F

```

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Listing 5—The Plot Module (Continued)

MCS-96 MACRO ASSEMBLER PLOT SERIAL PAGE 6

```

ERR LOC OBJECT          LINE SOURCE STATEMENT
25EC          198
25EC 8900002E          199 PRT_NUM:
25FD DF49             200 cmp yptr,#PLOT_RES_2 ; If value is less then minimum needed
201                201 be NNTLN ; for a plot, do not print value
202                202 push #2020H ; print 2 spaces then value
25F2 C92020          203 call con_out
25F5 2F19             204 call FFT_MODE,3,db_mode
25F7 3B000B          205 JBS
206                206
25FA             207 norm_mode:
25FA C82D0000          208 push PLOT_IN[yptr]
25FF C9000A          209 push #0A00H or 0000B)
2601 2F49             210 call PRINT_NUM
2603 2036             211 BR NNTLN
212
2605             212 db_mode:
2605 A32D00002E          213 ld yptr,plot_in[yptr]
260A 08012E          214 shr yptr,#1
260D AC2F00          215 ldbze ax,yptr+1
216                216
2610 C800             217 push ax
2612 C9020A          218 push #0A00H or 0010B)
2615 2F35             219 call PRINT_NUM
2617 C92E00          220 call #2EH
261A 2EF4             221 push con_out
222                222
261C E02E01          223 ldb ax+1,yptr ; high byte of ax = fractional portion of
261F 1100             224 clrb ax ; 10LOG(x)
225                225
2621 6DE60300          226 mulu ax,#3E6H ; if ax=FF00H then ax+2 now = 998 decimal
2625 370102          227 jbc ax+1,7,no_rnd
2628 0700             228 inc dx ; round value up
229                229
262A C800             230 no_rnd:
262A C90106          231 push dx ; dx=ax+2
262C 2F1B             232 call #600H or 0001B) ; print all numbers to three places
262F 2F1B             233 push #20H ; space
2631 C92000          234 call con_out
2634 2EDA             235 call #4264H ; "dB"
2636 C96442          236 push con_out
2639 2ED5             237 call $eject
238                238
239                239

```

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Listing 5—The Plot Module (Continued)

```

263B C90D0A      push    #0A0DH
263C 2ED0        call    CON_OUT
2640 C90000      push    #00H
2643 2ECB        call    CON_OUT
2645 C32086      push    #8620H
2648 2EC6        call    CON_OUT
264A C32100      push    #21H
264D 2EC1        call    con_out
264F 0730        inc      xval
2651 6502002C    add      xptr,#2
2655 838002C    cmp      xptr,#62
2659 D2022758    ble     nxt_row
265E             Done:
2660 2EAE        push    #0A0DH
2662 C9000C      call    CON_OUT
2665 2EA9        push    #0C00H
2667 F0          call    con_out
2668             RET
2669             END

```

ASSEMBLY COMPLETED, NO ERROR(S) FOUND.

```

; Setup for next line
; CRLF
; nul
; 7 spaces
; !
; Start printing next row
; CRLF ; Form feed for next graph
; null,FF

```

At the end of the plot, a form feed is given to set the printer up for the next graph. Our printer would frequently miss the character after a CRLF. To solve this problem, a null (ASCII 0) is sent after every CRLF to make sure the printer is ready for the next line. This has been found to be a problem with many devices running at close to their maximum capacity, and the nulls work well to solve it.

With the plot completed, the program begins to run again by taking another set of A to D samples.

11.0 USING THE FFT PROGRAM

The program can be used with either real or tabled data. If real data is used, the signal is applied to analog channel 1. The program as written performs A/D samples at 100 microsecond intervals, collecting the 64 samples in 6.4 milliseconds. This sets the sampling window frequency at 156 Hz. If tabled data is used, 64 words of data should be placed in the location pointed to by DATA0 in the TABLE_LOAD routine of the Main Module.

Program control is specified by FFT_MODE which is loaded in the main module. Also within the main module are settings which control the A to D buffer routine and the Plot routine. The intention was to have only one module to change and recompile to vary parameters in the entire program.

The program modules are set up to run one-at-a-time so that the code would be easy to understand. Additionally, the Plot routine takes so long relative to the other sections, that it doesn't pay to try to overlap code sections. If this code were to be converted to run a process instead of print a graph, it might be worthwhile to run the FFT and the A/D routines at the same time.

If the goal of a modified program is to have the highest frequency sampling possible, it might be desirable to streamline the A/D section and run it without interruption. When the A to D routine was complete the FFT routine could be started. The reasoning behind this is that at the fastest A/D speeds the processor will be almost completely tied up processing the A/D information and storing it away. Using an interrupt based A/D routine would slow things down.

A set of programs which will perform a FFT has been presented in this application note. These programs are available from the INSITE users library as program CA-26. More importantly, dozens of programing examples have been made available, making it easier to get started with the 8096. Examples of how to use the hardware on the 8096 have already appeared in AP-248, "Using The 8096". These two applications notes form a good base for the understanding of MCS-96 microcontroller based design.

12.0 APPENDIX A - MATRICES

Matrices are a convenient way to express groups of equations. Consider the complex discrete Fourier Transform in equation 9, with $N = 4$.

$$Y_n = \sum_{k=0}^3 X(k) W^{nk} \quad n = 0, 1, 2, 3$$

This can be expanded to

$$\begin{aligned} Y(0) &= X(0) W^0 + X(1) W^0 + X(2) W^0 + X(3) W^0 \\ Y(1) &= X(0) W^0 + X(1) W^1 + X(2) W^2 + X(3) W^3 \\ Y(2) &= X(0) W^0 + X(1) W^2 + X(2) W^4 + X(3) W^6 \\ Y(3) &= X(0) W^0 + X(1) W^3 + X(2) W^6 + X(3) W^9 \end{aligned}$$

In matrix notation, this is shown as

$$\begin{bmatrix} Y(0) \\ Y(1) \\ Y(2) \\ Y(3) \end{bmatrix} = \begin{bmatrix} W^0 & W^0 & W^0 & W^0 \\ W^0 & W^1 & W^2 & W^3 \\ W^0 & W^2 & W^4 & W^6 \\ W^0 & W^3 & W^6 & W^9 \end{bmatrix} \begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ X(3) \end{bmatrix}$$

The first step to simplifying this is to reduce the center matrix. Recalling that

$$W^N = W^{N \bmod N} \quad \text{and} \quad W^0 = 1$$

The matrix can be reduced to have less non-trivial multiplications.

$$\begin{bmatrix} Y(0) \\ Y(1) \\ Y(2) \\ Y(3) \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & W^1 & W^2 & W^3 \\ 1 & W^2 & W^0 & W^2 \\ 1 & W^3 & W^2 & W^1 \end{bmatrix} \begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ X(3) \end{bmatrix}$$

The square matrix can be factored into

$$\begin{bmatrix} Y(0) \\ Y(2) \\ Y(1) \\ Y(3) \end{bmatrix} = \begin{bmatrix} 1 & W^0 & 0 & 0 \\ 1 & W^2 & 0 & 0 \\ 0 & 0 & 1 & W^1 \\ 0 & 0 & 1 & W^3 \end{bmatrix} \begin{bmatrix} 1 & 0 & W^0 & 0 \\ 0 & 1 & 0 & W^0 \\ 1 & 0 & W^2 & 0 \\ 0 & 1 & 0 & W^2 \end{bmatrix} \begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ X(3) \end{bmatrix}$$

For this equation to work, the $Y(1)$ and $Y(2)$ terms need to be swapped, as shown above. This procedure is a Bit Reversal, as described in the text.

Multiplying the two rightmost matrices results in

$$\begin{aligned} &X(0) + X(2) W^0 \\ &X(1) + X(3) W^0 \quad \text{requiring 4 complex multiplications} \\ &X(0) + X(2) W^3 \quad \text{\& 4 complex additions} \\ &X(1) + X(3) W^2 \end{aligned}$$

Noting that $W^0 = -W^2$, 2 of the complex multiplications can be eliminated, with the following results

$$\begin{aligned} &X(0) + X(2) W^0 \\ &X(1) + X(3) W^0 \quad \text{requiring 2 complex multiplications} \\ &X(0) - X(2) W^0 \quad \text{and 4 complex additions} \\ &X(1) - X(3) W^0 \end{aligned}$$

Since $W^1 = -W^3$, a similar result occurs when this vector is multiplied by the remaining square matrix. The resulting equations are:

$$\begin{aligned} Y(0) &= (X(0) + X(2) W^0) + W^0 (X(0) + X(3) W^0) \\ Y(2) &= (X(0) + X(2) W^0) - W^0 (X(1) + X(3) W^0) \\ Y(1) &= (X(0) - X(2) W^0) + W^1 (X(1) - X(3) W^0) \\ Y(3) &= (X(0) - X(2) W^0) - W^1 (X(1) - X(3) W^0) \end{aligned}$$

The number of complex multiplications required is 4, as compared with 16 for the unfactored matrix.

In general, the FFT requires

$$\frac{N * \text{EXPONENT}}{2} \text{ complex multiplications}$$

and

$$N * \text{EXPONENT} \text{ complex additions}$$

where

$$\text{EXPONENT} = \log_2 N$$

A standard Fourier Transform requires

$$N^2 \text{ complex multiplications}$$

and

$$N(N-1) \text{ complex additions}$$

13.0 APPENDIX B - PLOTS

The following plots are examples of output from the FFT program. These plots were generated using tabled data, but very similar plots have also been made using the analog input module. Typically, a plot made using the analog input module will not show quite as much power at each frequency and will show a positive value for the DC component. This is because it is difficult to get exactly a full-scale analog input with no DC offset.

Plot 1 is a Magnitude plot of a square wave of period NT.

Plot 2 is the same data plotted in dB. Note how the dB plot enhances the difference in the small signal values at the high frequencies.

Plot 3 shows the windowed version of this data. Note that the widening of the bins due to windowing shows energy in the even harmonics that is not actually present. For data of this type a different window other than Hanning would normally be used. Many window types are available, the selection of which can be determined by the type of data to be plotted.³

Plot 4 shows a sine wave of period NT/7 or frequency 7/NT.

Plot 5 shows the same input with windowing. Note the signal shown in bins 6 and 8.

Plot 6 shows a sine wave of period NT/7.5. Note the noise caused by the discontinuity as discussed earlier.

Plot 7 uses windowing on the data used for plot 6. Note the cleaner appearance.

Plot 8 shows a sine wave input of magnitude 0.707 and period NT/7.5.

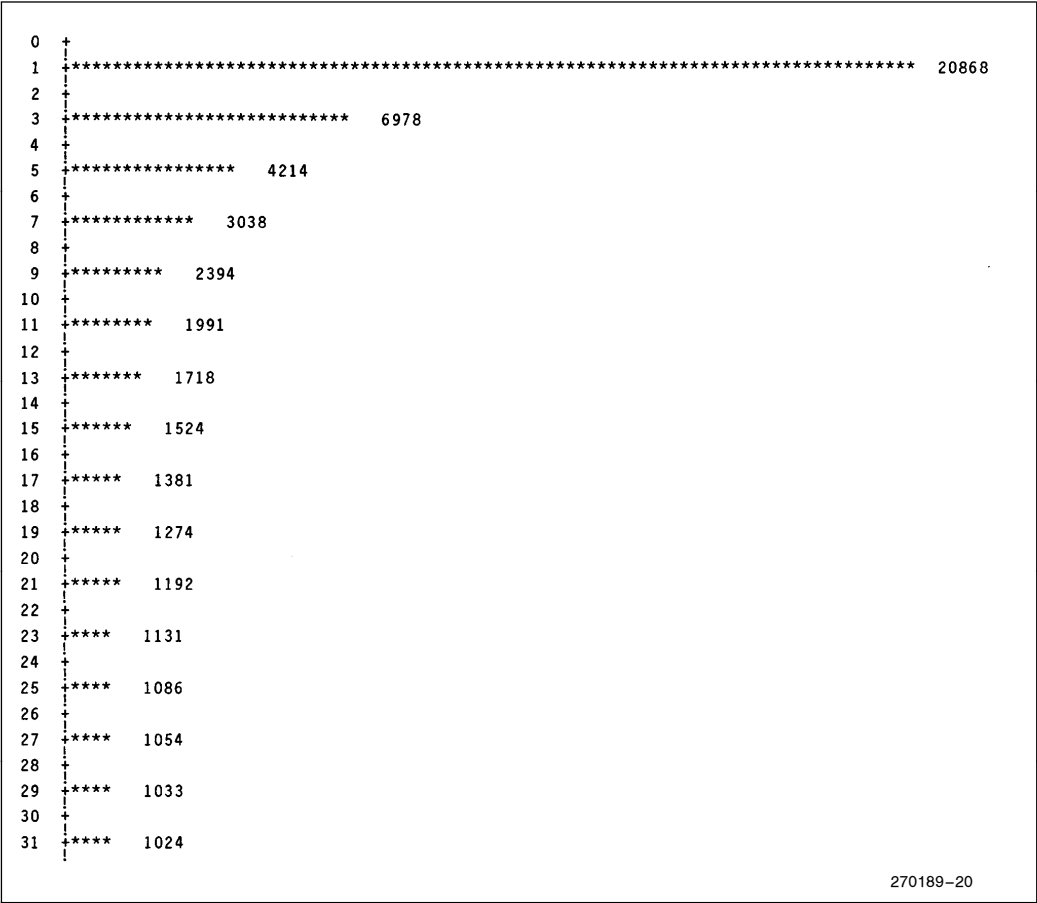
Plot 9 shows same input with windowing.

Plot 10 shows a sine wave of magnitude 0.707/16 and period NT/11.

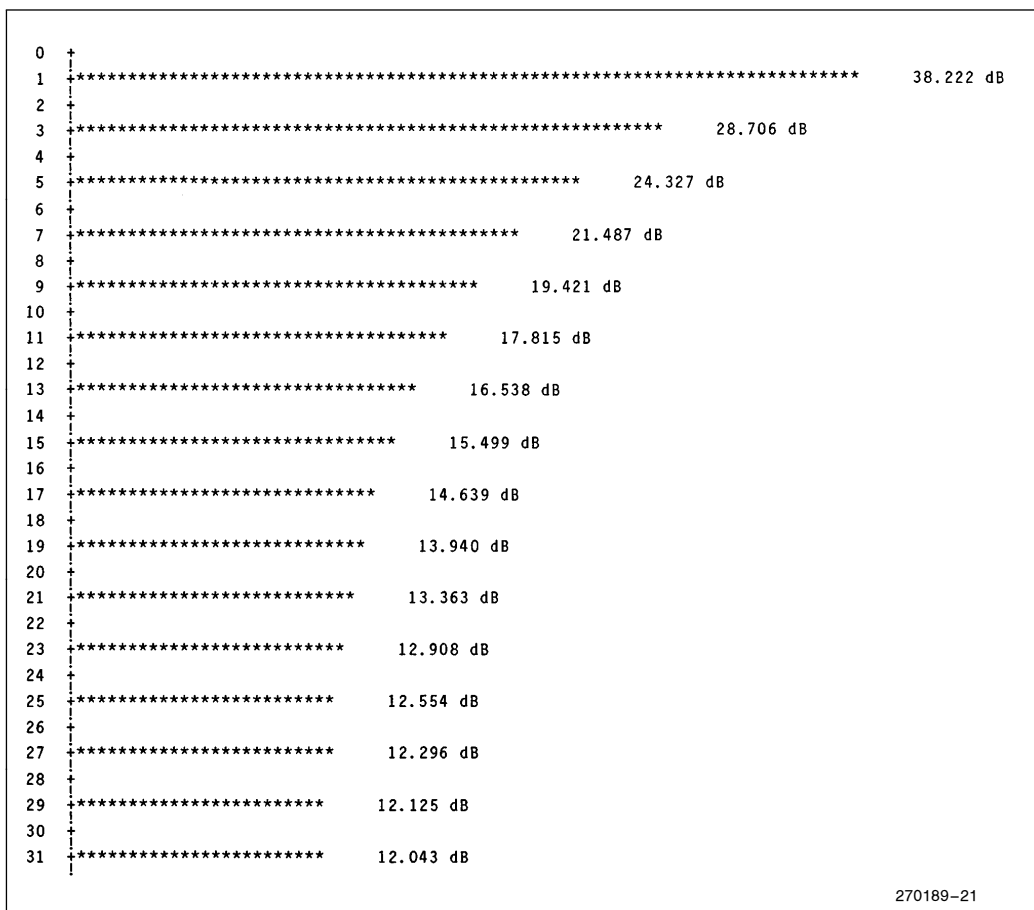
Plot 11 shows the same input with windowing. Note that there is no power shown in bins 10 and 12. This is because at 6 dB down from 3 dB they are nearly equal to zero.

Plot 12 uses the sum of the signals for plots 8 and 10 as inputs. Note that the component at period NT/11 is almost hidden.

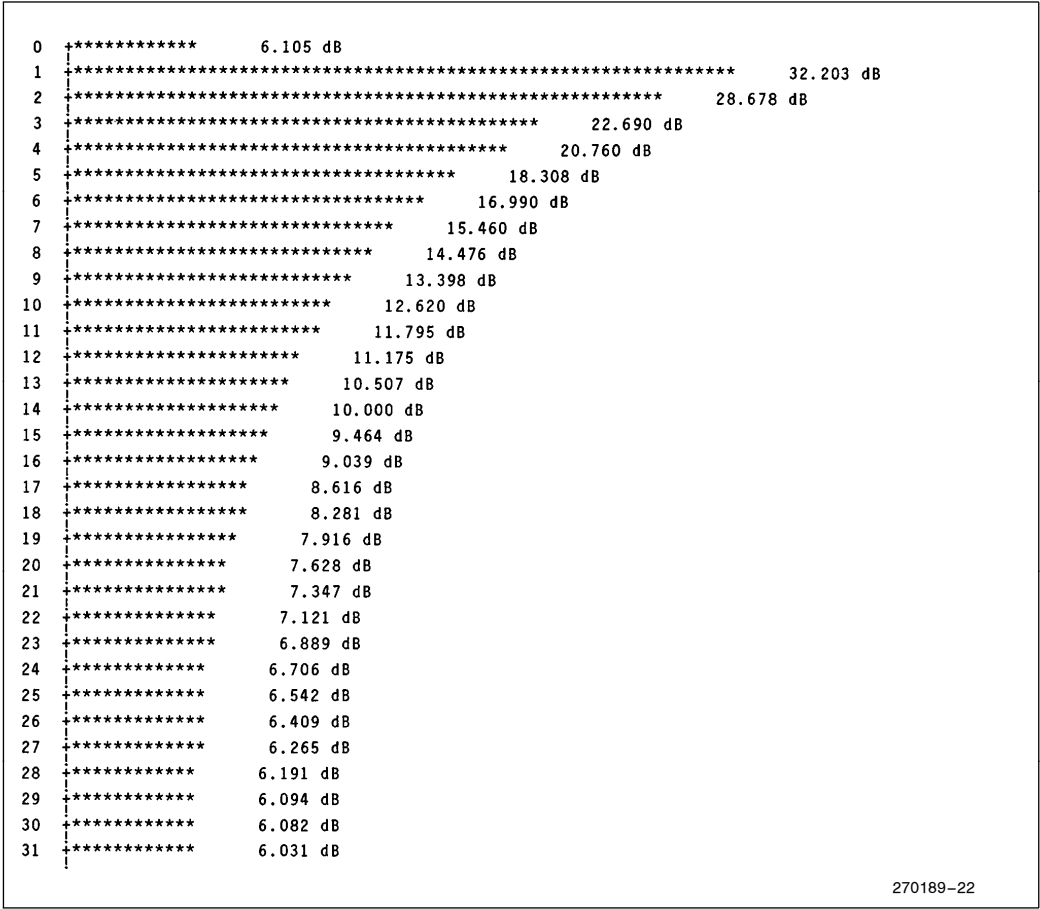
Plot 13 uses the same signal as plot 12 but applies windowing. Now the period component at NT/11 can easily be seen. The Hanning window works well in this case to separate the signal from the leakage. If the signals were closer together the Hanning window may not have worked and another window may have been needed.



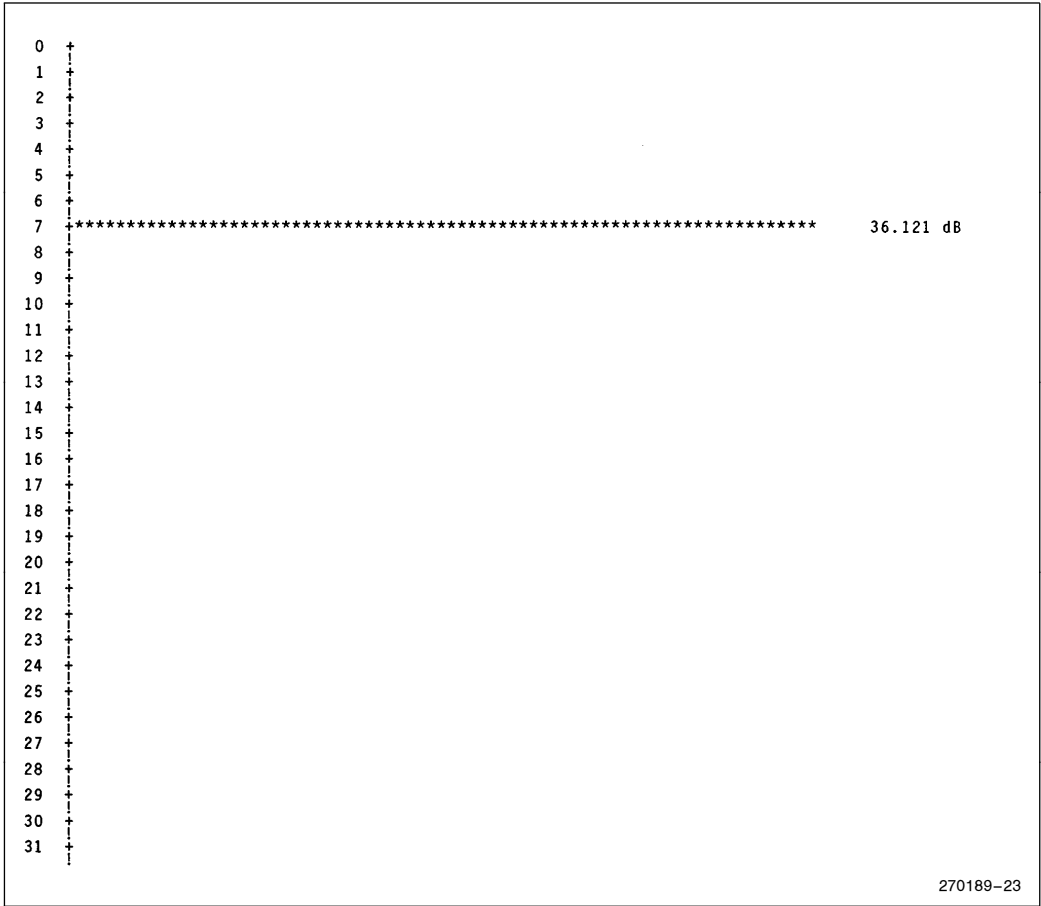
Plot 1—Magnitude Plot of Squarewave



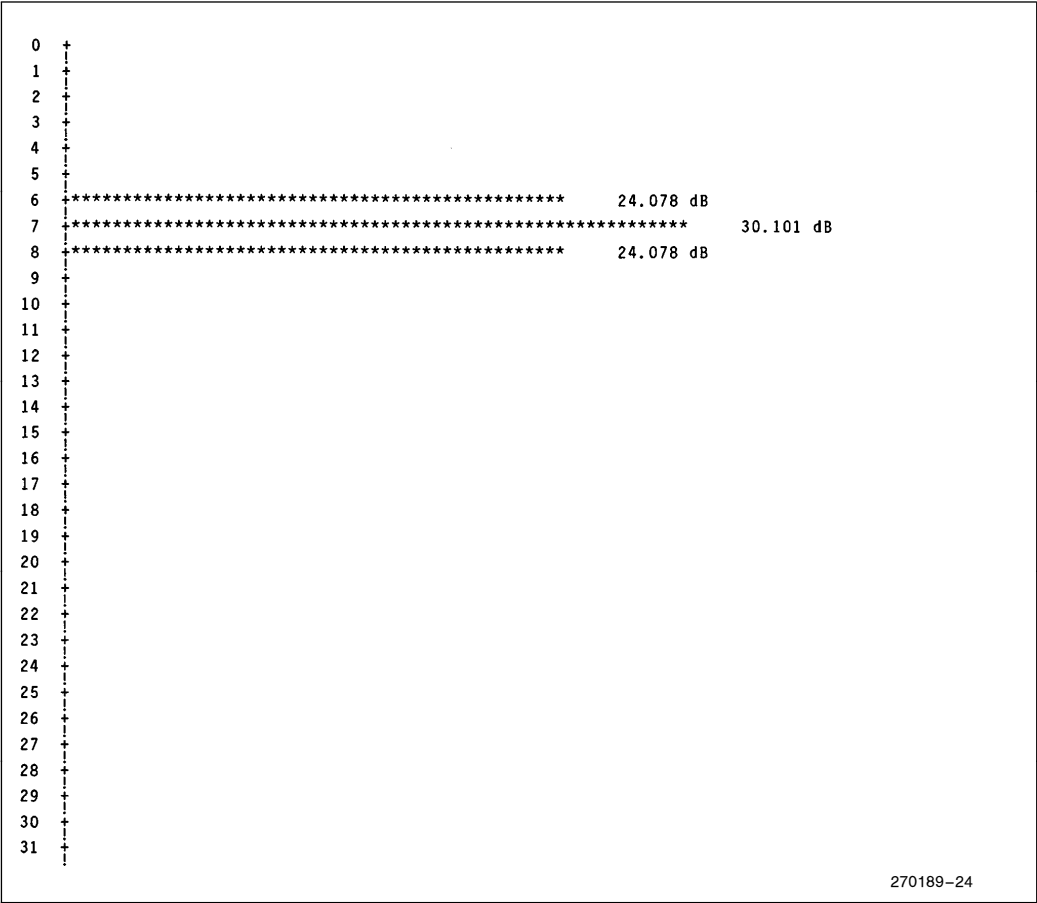
Plot 2—Decibel Plot of Squarewave



Plot 3—Plot of Squarewave with Window



Plot 4—Sin (7.0X) without Window



Plot 5—Sin (7.0X) with Window

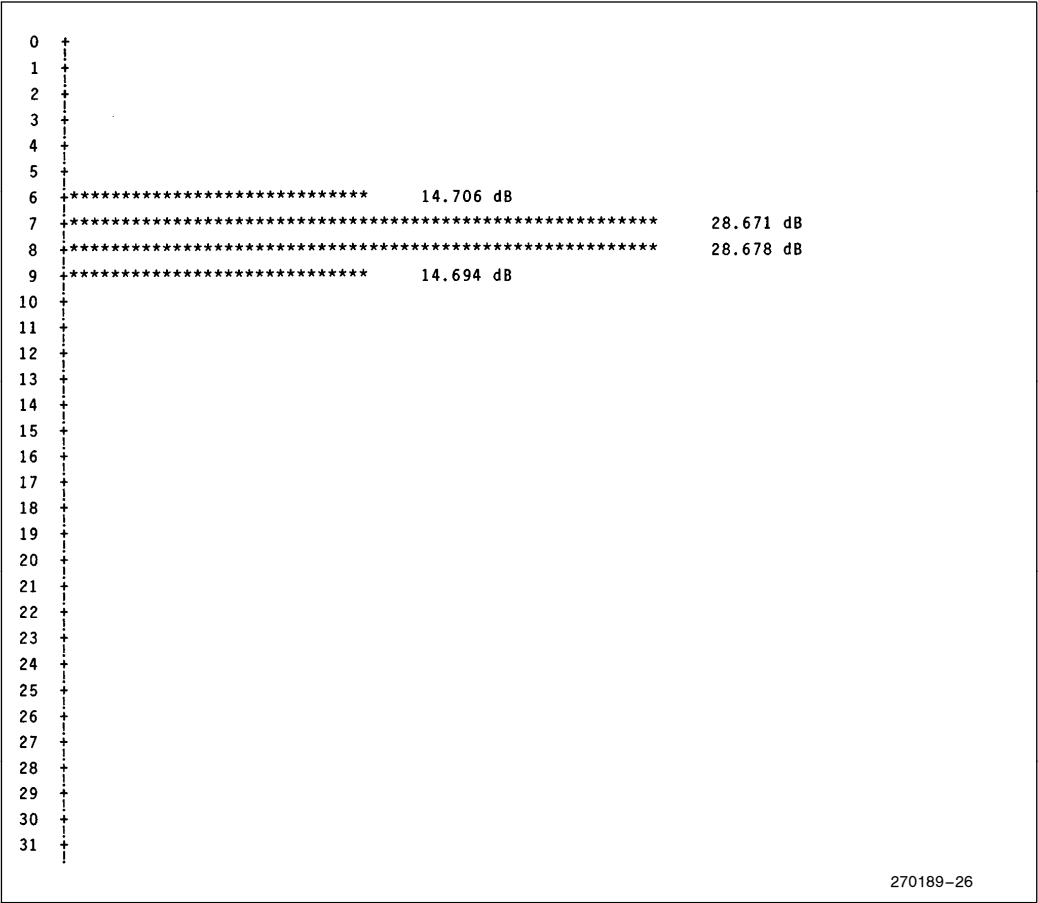
```

0 +***** 14.265 dB
1 +***** 14.444 dB
2 +***** 14.943 dB
3 +***** 15.865 dB
4 +***** 17.308 dB
5 +***** 19.569 dB
6 +***** 23.421 dB
7 +***** 32.441 dB
8 +***** 31.971 dB
9 +***** 22.012 dB
10 +***** 17.199 dB
11 +***** 13.943 dB
12 +***** 11.472 dB
13 +***** 9.483 dB
14 +***** 7.819 dB
15 +***** 6.402 dB
16 +***** 5.164 dB
17 +***** 4.090 dB
18 +***** 3.152 dB
19 +***** 2.308 dB
20 +*** 1.546 dB
21 +** 0.901 dB
22 +* 0.300 dB
23 +
24 +
25 +
26 +
27 +
28 +
29 +
30 +
31 +

```

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Plot 6—Sin (7.5X) without Window



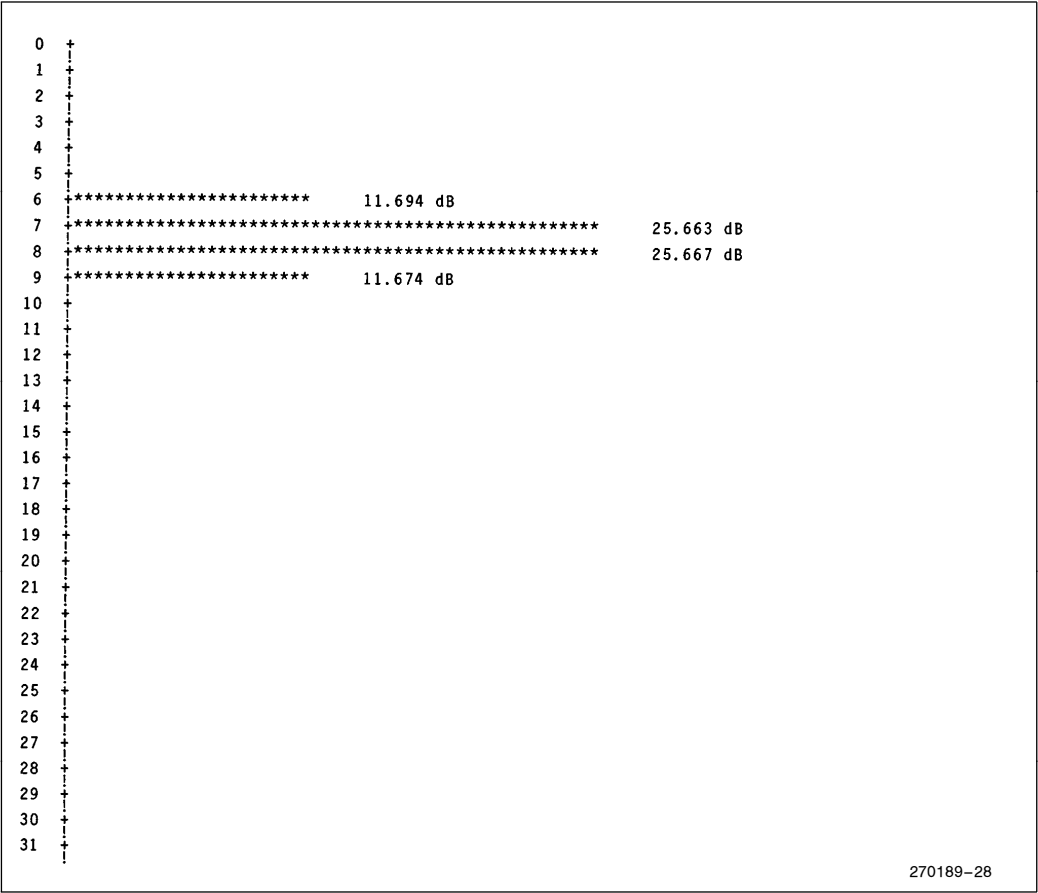

```

0 +***** 11.242 dB
1 -***** 11.417 dB
2 +***** 11.936 dB
3 -***** 12.846 dB
4 +***** 14.296 dB
5 -***** 16.561 dB
6 +***** 20.409 dB
7 -***** 29.425 dB
8 +***** 28.959 dB
9 -***** 18.994 dB
10 +***** 14.187 dB
11 -***** 10.936 dB
12 +***** 8.472 dB
13 -***** 6.468 dB
14 +***** 4.819 dB
15 -***** 3.382 dB
16 +***** 2.152 dB
17 -** 1.082 dB
18 +
19 +
20 +
21 +
22 +
23 +
24 +
25 +
26 +
27 +
28 +
29 +
30 +
31 +

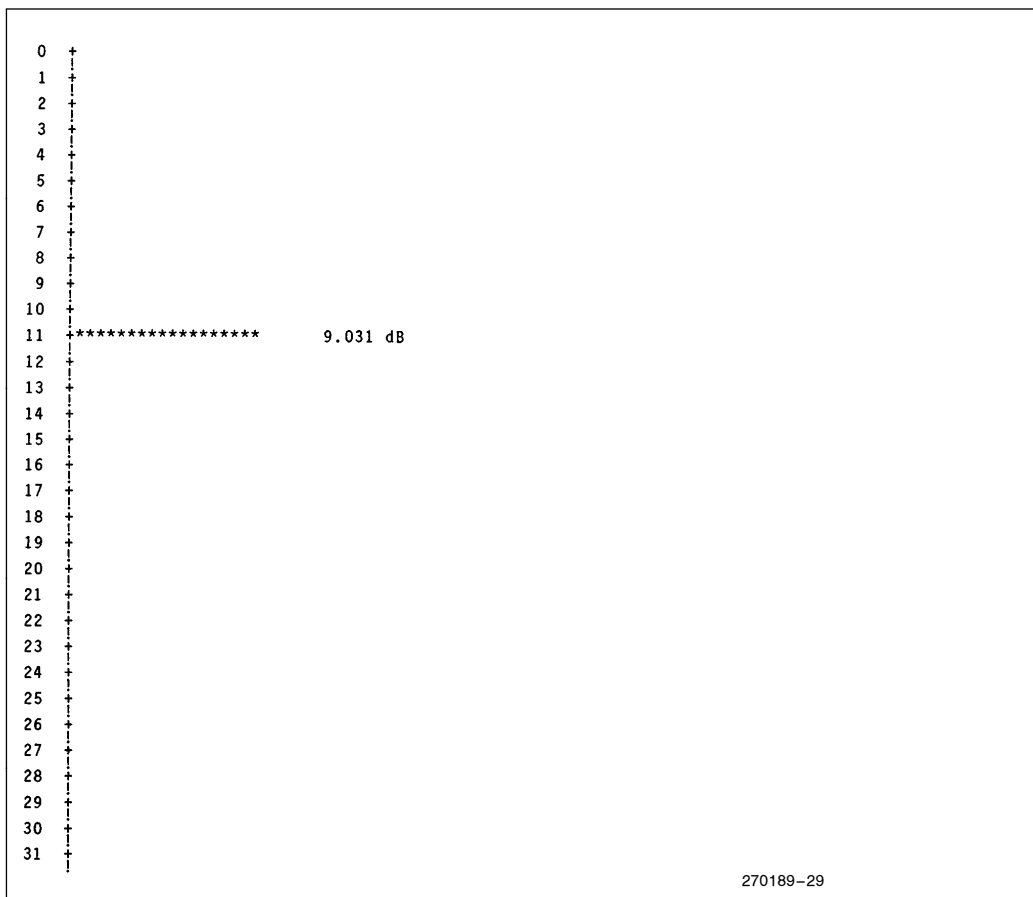
```

270189-27

Plot 8— $0.707 \cdot \sin(7.5X)$ without Window



Plot 9—0.707 * Sin (7.5X) with Window





Plot 11— $0.707/16 * \sin(11X)$ with Window

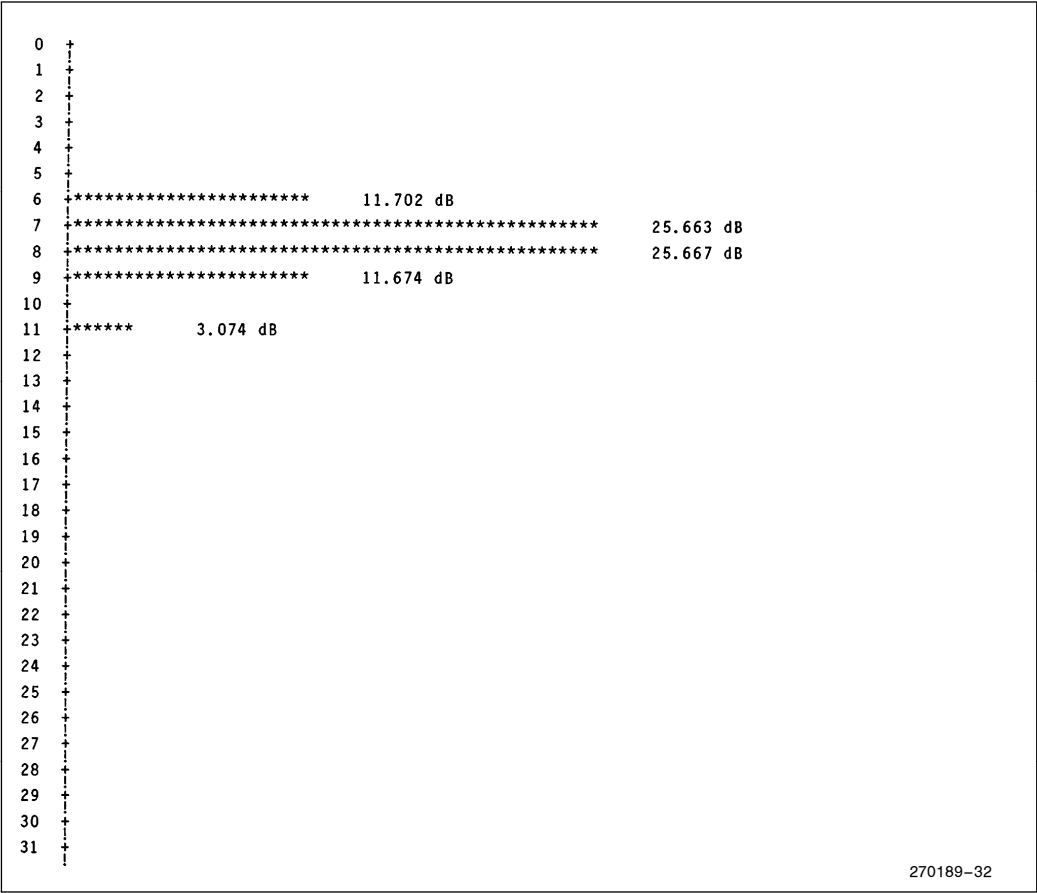
```

0 +***** 11.242 dB
1 +***** 11.425 dB
2 +***** 11.936 dB
3 +***** 12.846 dB
4 +***** 14.296 dB
5 +***** 16.561 dB
6 +***** 20.409 dB
7 +***** 29.425 dB
8 +***** 28.959 dB
9 +***** 19.000 dB
10 +***** 14.187 dB
11 +***** 13.105 dB
12 +***** 8.472 dB
13 +***** 6.483 dB
14 +***** 4.819 dB
15 +***** 3.382 dB
16 +**** 2.152 dB
17 +** 1.082 dB
18 +
19 +
20 +
21 +
22 +
23 +
24 +
25 +
26 +
27 +
28 +
29 +
30 +
31 +

```

270189-31

Plot 12— $0.707 (\sin (7.5X) + \frac{1}{16} \sin (11X))$ without Window



Plot 13— $0.707 (\sin (7.5X) + \frac{1}{16} \sin (11X))$ with Window

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